



# 890 Quickstart Manual

## 890SD (Standalone) Drive Frames B, C & D

HA471071U000 Issue 3 (ISO A4)  
HA471071U001 Issue 3 (American Quarto)

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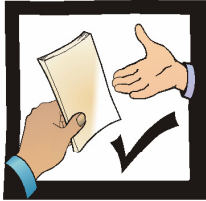
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# Safety

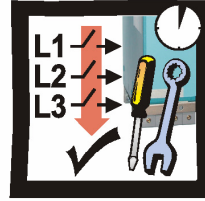
**IMPORTANT** Please read this information **BEFORE** installing the equipment.



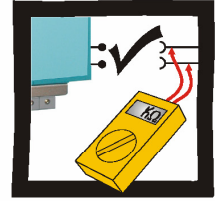
This manual is for anyone installing and operating this unit.



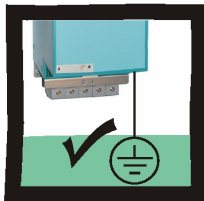
You must be technically competent to install and operate this unit.



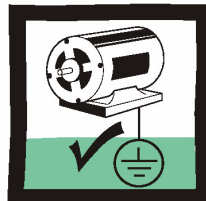
Before working on the unit, isolate the mains supply from terminals L1, L2 and L3 and wait 3 minutes.



Disconnect the unit from circuits when doing high voltage resistance checks.



The unit must be **permanently earthed** due to the high earth leakage current.



The drive motor must be connected to an appropriate safety earth.



Electrostatic discharge sensitive parts : observe static control precautions.



Copy existing 890 parameters to any replacement 890 unit

## Hazards to Personnel

This equipment can endanger life through rotating machinery and high voltages. Failure to observe the following will constitute an **ELECTRICAL SHOCK HAZARD**.

Metal parts may reach a temperature of 70 degrees Centigrade in operation.

Before working on the equipment, ensure isolation of the mains supply from terminals L1, L2 and L3. The equipment contains high value capacitors which discharge slowly after removal of the mains supply. Wait for at least 3 minutes for the dc link terminals (DC+ and DC-) to discharge to safe voltage levels (<50V). Measure the DC+ and DC- terminal voltage with a meter to confirm that the voltage is less than 50V.

Do not apply external voltage sources (mains supply or otherwise) to any of the braking terminals (DBR+, DBR-, DC+, INT or EXT).

## Application Risk

The specifications, processes and circuitry described herein are for guidance only and may need to be adapted to the user's specific application.

Parker SSD Drives does not guarantee the suitability of the equipment described in the Manual for individual applications.

---

## Risk Assessment

Under fault conditions, power loss or other operating conditions not intended, the equipment may not operate as specified. In particular:

- The motor speed may not be controlled
- The direction of rotation of the motor may not be controlled
- The motor may be energised

---

## Accessibility

All live power terminals are IP20 rated only, since the equipment is intended to be installed within a normally-closed cubicle or enclosure, which itself requires a tool to open.

---

## Protective Insulation

- All control and signal terminals are SELV, i.e. protected by double insulation. Ensure all wiring is rated for the highest system voltage.

**NOTE** *Thermal sensors contained within the motor must be single/basic insulated.*

- All exposed metalwork in the Drive is protected by basic insulation and bonding to a safety earth.

---

## RCDs

Not recommended for use with this product. Where their use is mandatory, use only Type B RCDs (EN61009).

---

## Caution

This is a product of the restricted sales distribution class according to IEC 61800-3. It is designated as “professional equipment” as defined in EN61000-3-2. Permission of the supply authority shall be obtained before connection to the low voltage supply.

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# Introduction

The 890SD Standalone Drive is designed for speed control of standard ac 3-phase motors.

- Control it remotely using configurable analogue and digital inputs and outputs.
- Control it locally using the 6511 Keypad.
- Use the Design System Explorer Configuration Tool (DSE 890) to give access to parameters, diagnostic messages, trip settings and application programming.
- Fit Options to the unit to give serial communications and closed loop speed control.

**IMPORTANT** Motors used must be suitable for Inverter duty.

## About this QuickStart

**This QuickStart will:**

- Familiarise you with the terminals and operation of the unit.
- Provide **\*basic** installation details and a quick set-up procedure.
- Show you how to Autotune the drive and start the motor.

*\* Because the 890 is a system product and we have no knowledge of your application, we detail the quickest way to power-up the drive using a simple earthing scheme with minimal control wiring. Refer to the full Engineering Reference Manual for items not covered in this QuickStart.*

**Provided with every 890 unit is a :**

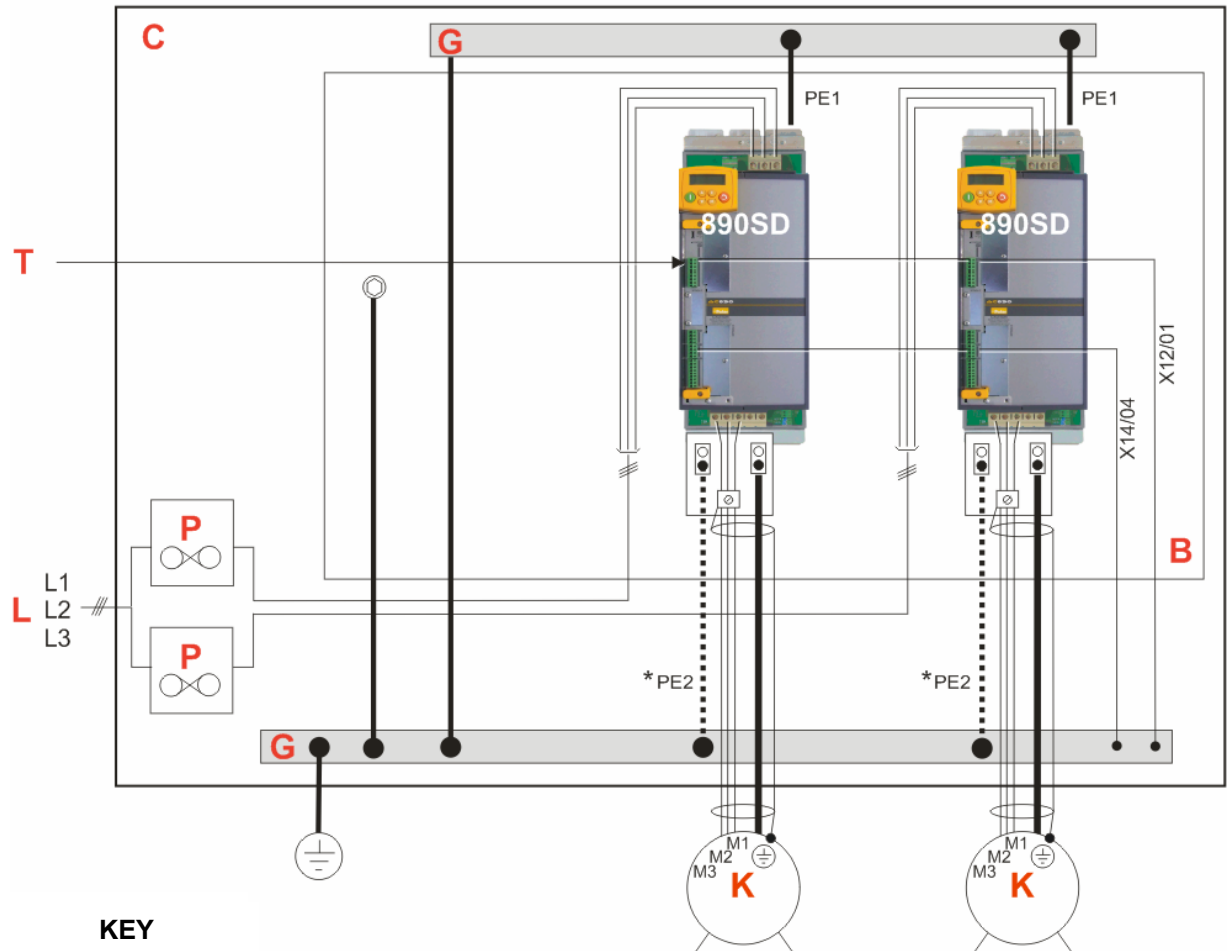
- Quickstart
- Compact disk containing the Engineering Reference Manual and DSE Configuration Tool
- 890 Installation Kit and instruction leaflet
- 6511 Keypad
- Customer-ordered Options

**This QuickStart assumes that:**

- You are a qualified technician with experience of installing this type of equipment.
- You are familiar with the relevant standards and Local Electric Codes (which take precedence).
- You have read and understood the Safety information provided at the front of this QuickStart.
- You realise that this guide contains only basic information and that you may need to refer to the Engineering Reference Guide to complete your installation.

# Installation

A simplified installation is shown below. This installation is **not** EMC compliant. For European installations and countries with EMC legislation refer to the 890 Engineering Reference Manual, Appendix C.



## KEY

- B** Back-plate
- C** Cubicle
- G** Supply Protective Earth/Ground
- K** Motor (M1, M2, M3)
- L** 3Ø Power Supply Cable (L1, L2, L3)
- P** Fuse or circuit breaker
- T** Control Wiring terminals

## 890 Installation Kit

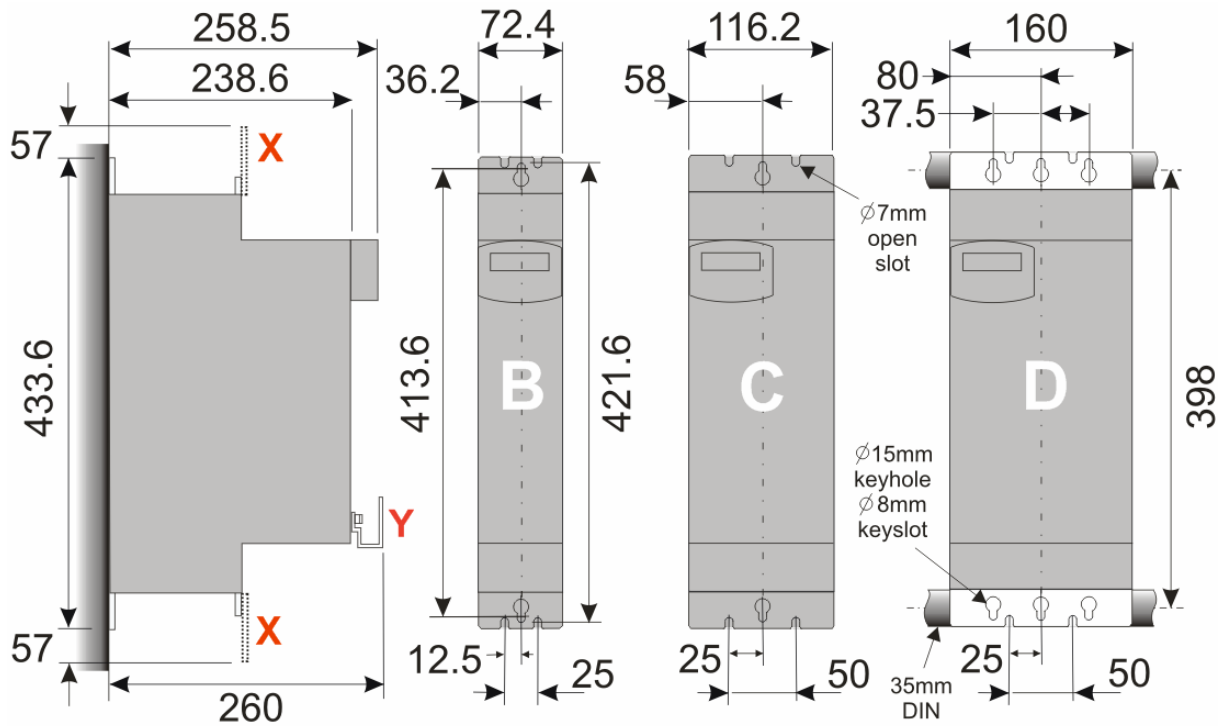
The 890 Installation Kit is shown attached to the bottom of the 890SD units in the diagram. It can also be fitted to the top of the unit.

The kit provides several options for earth/ground connections. It also includes the brackets for DIN rail mounting the unit. Refer to the instructions in the kit and use the appropriate parts.

### \* Permanent Earthing

The unit must be **permanently earthed** according to EN 50178: A cross-section conductor of at least 10mm<sup>2</sup> is required. This can be achieved either by using a single conductor (PE) or by laying a second conductor through separate terminals (PE2 where provided) and electrically in parallel.

# Dimensions

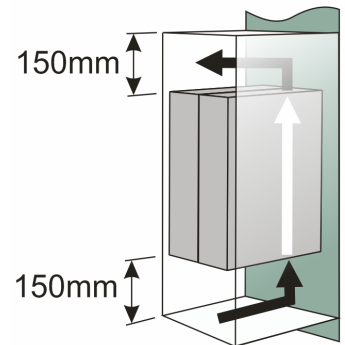


Dimensions are in millimeters (X : Power Bracket - 890 Installation Kit, Y : Control Bracket)

The units must be installed in a cubicle. Mount the drive using the keyholes and slots or on a 35mm DIN rail using the 890 Installation Kit supplied.

## Ventilation

The drives can be mounted side-by-side with no clearance. A minimum of 150mm (6 inches) free-air space must be allowed at the top and bottom of each drive. If mounting drives above or below other equipment, the top and bottom distances should be added for overall clearance between drives.



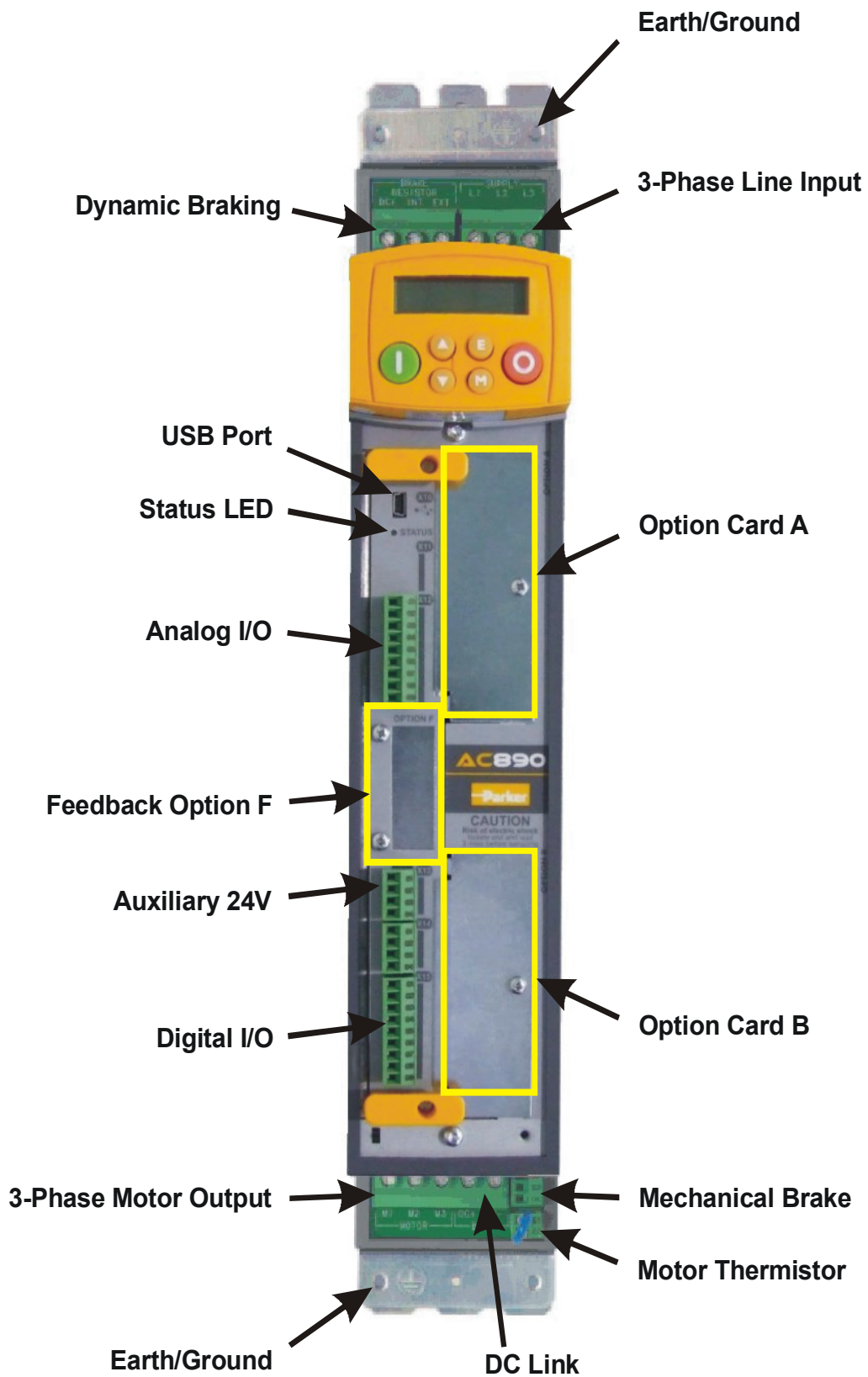
## Environmental Conditions

Operating ambient temperature      0°C to 45°C (32°F to 113°F)

Enclosure rating                              IP20 – UL(cUL) Open type

Atmosphere                                      Dust free, non flammable, non-corrosive, <85% humidity, non-condensing

# Overview





# 3-Phase Connections

1

Connect 3-phase power in any order to L1, L2, L3.  
Maximum wire sizes:

Frame B: 6mm<sup>2</sup>/10AWG - 0.5Nm  
Frame C: 10mm<sup>2</sup>/8AWG - 1.2Nm  
Frame D: 16mm<sup>2</sup>/4AWG - 2.4Nm

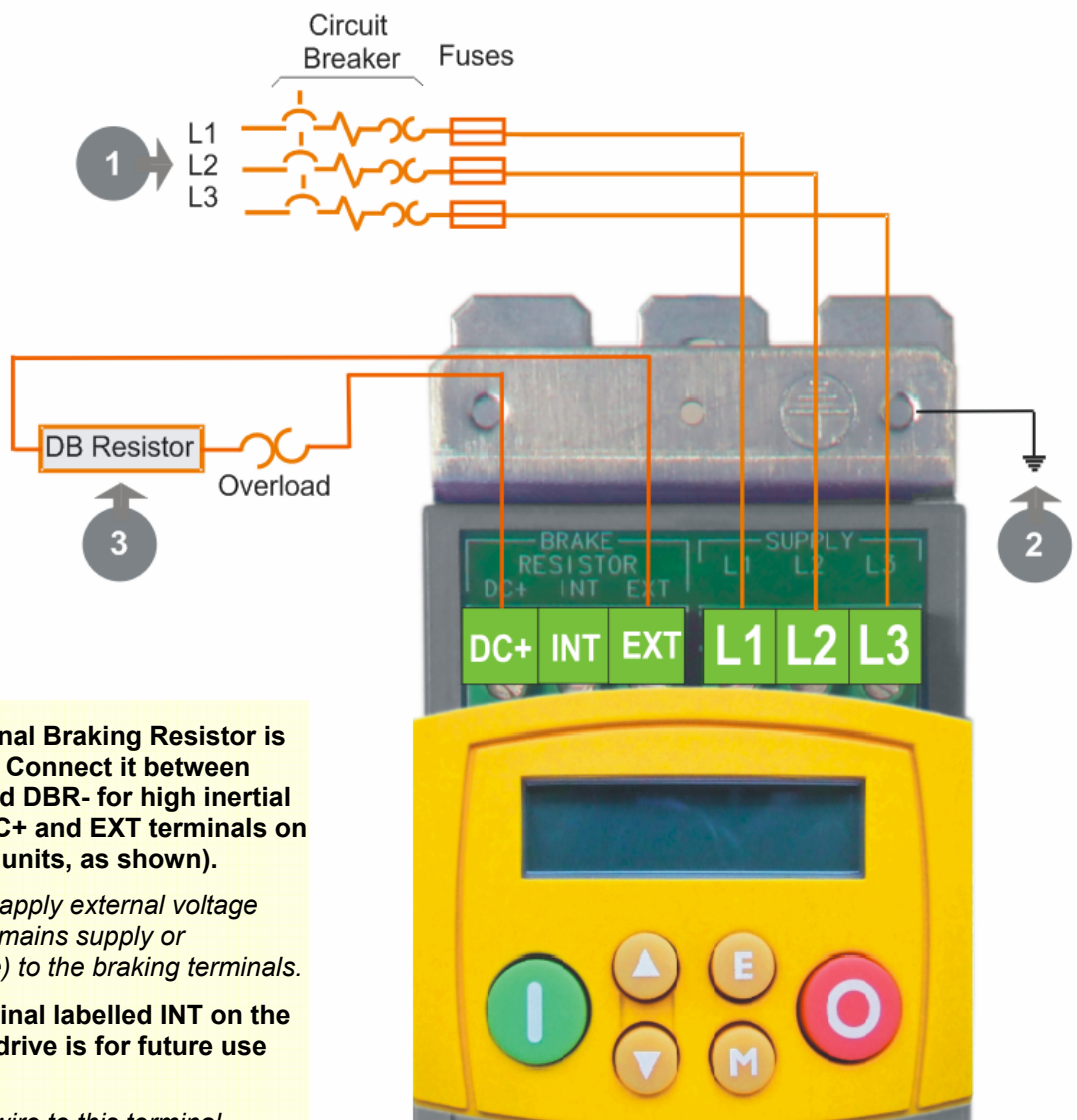
- Use branch circuit protection (circuit breaker and/or fuses)

Refer to Appendix D for Drive Rating details

2

Connect the earth/ground wire to the top ground bracket.  
Maximum wire sizes:

Frame B: 6mm<sup>2</sup>/10AWG  
Frame C: 10mm<sup>2</sup>/8AWG  
Frame D: 16mm<sup>2</sup>/4AWG



- An External Braking Resistor is optional. Connect it between DBR+ and DBR- for high inertial loads (DC+ and EXT terminals on Frame B units, as shown).

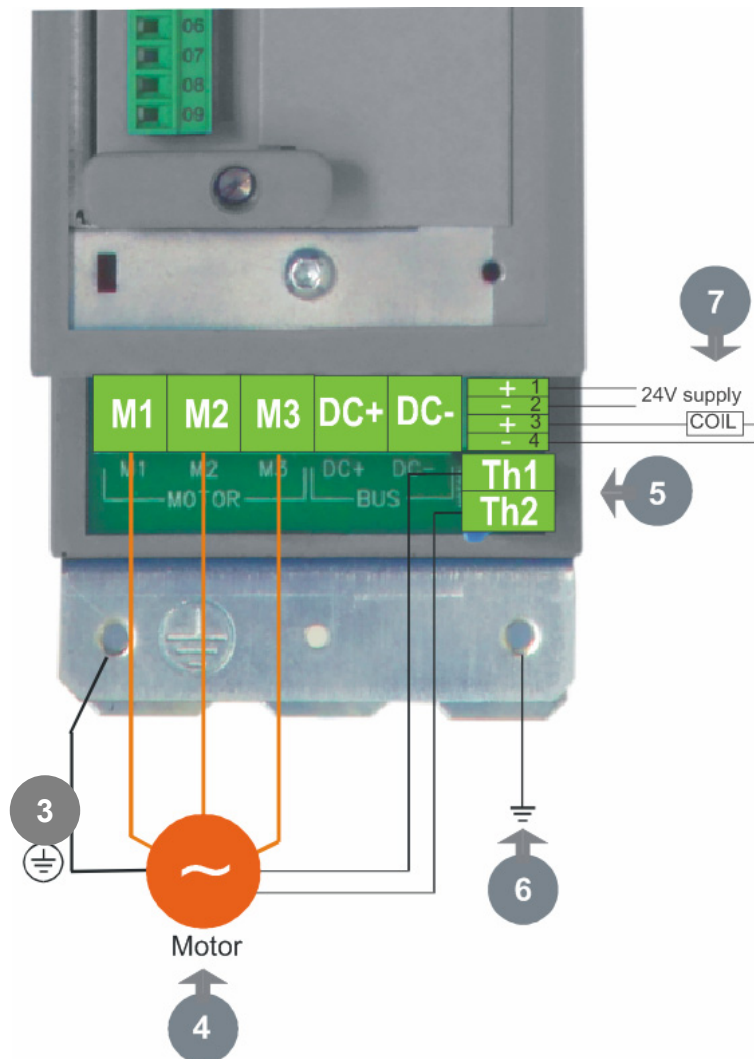
*DO NOT* apply external voltage sources (mains supply or otherwise) to the braking terminals.

- The terminal labelled INT on the frame B drive is for future use only.

*DO NOT* wire to this terminal.

- We recommend using a thermal overload switch to protect the braking circuit.

# Motor Connections



**4** Connect motor leads to M1, M2, M3. Maximum wire sizes:  
**Frame B: 4mm<sup>2</sup>/12AWG**  
**Frame C: 10mm<sup>2</sup>/8AWG**  
**Frame D: 16mm<sup>2</sup>/4AWG**

- Connect the earth/ground wire from the terminal box of the motor directly to the bottom ground bracket. Maximum wire sizes:

**Frame B: 4mm<sup>2</sup>/12AWG**  
**Frame C: 10mm<sup>2</sup>/8AWG**  
**Frame D: 16mm<sup>2</sup>/4AWG**

- If not using shielded cable, run motor leads in an enclosed metal conduit grounded at both ends

**5** Connect motor thermal switch or thermistor to Th1, Th2. Drive will trip when the thermal switch opens, or when the thermistor resistance exceeds 4kΩ maximum (PTC Type A : IEC 34-11 Part 2)

- If the motor does not have a protective device (thermistor), link these terminals. The drive needs the thermistor inputs connected for it to run.

**6** Connect the earth/ground wire to the bottom ground bracket. Maximum wire sizes:  
**Frame B: 4mm<sup>2</sup>/12AWG**  
**Frame C: 10mm<sup>2</sup>/8AWG**  
**Frame D: 16mm<sup>2</sup>/4AWG**

**7** Connect the 24V DC brake supply to terminals 1 and 2, and connect the brake terminals to 3 and 4. The brake coil is energized when the drive runs.

# 890SD Control Connections

## A Speed Reference

- Connect a 10kΩ potentiometer at terminal block X12 (Analog I/P 3)
  - High (CW): terminal X12/08
  - Wiper: terminal X12/04
  - Low (CCW): terminal X12/01
- Connect the shield to earth/ground at the bottom ground bracket

OR

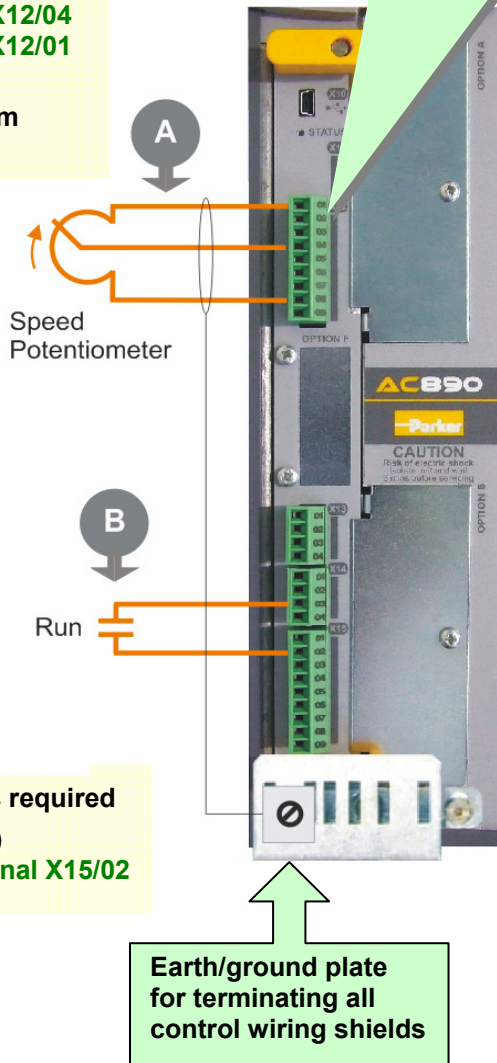
- External 2-wire speed reference between terminals X12/01(-) and X12/04(+)
- Connect the shield to earth ground at the bottom ground bracket

## B Sequencing

Connect volt-free contacts as required

- RUN (maintained contact) terminal X14/03 and terminal X15/02

The control terminals will accept a single wire of size 1.5mm<sup>2</sup>/16AWG. For two wires per terminal, use smaller gauge wire such as 0.5mm<sup>2</sup>/22AWG.



## Analog

- SPEED FEEDBACK**  
10V = ±100% speed at terminal X12/0 6
- TORQUE FEEDBACK**  
10V = ±200% torque at terminal X12/07
- ANALOG COMMON**  
0V at terminal X12/0 1

## Digital

- DRIVE HEALTH**  
Relay dry contact (24V rated) at terminal X14/01 and terminal X14/02
- RUNNING**  
24V sourcing output at terminal X15/08
- ZERO SPEED**  
24V sourcing output at terminal X15/09
- DIGITAL COMMON**  
0V at terminal X14/04

This is a basic connection diagram.

For more detailed information on control connections, refer to Appendix C.

# 890SD Feedback Connections

**This section is only for closed loop vector and induction servo applications. Skip this page if there is no encoder or resolver mounted on the motor**

## Incremental Pulse Encoders

The default settings for the drive are for 2048 line, quadrature, incremental pulse encoders with differential outputs operating from a 10VDC supply.

- Z channel (Marker pulse) connections are not necessary for running the drive, but inputs are provided for positioning and servo applications. The supply voltage to the encoder is set in the Quick Setup menu. Range 10 VDC to 20 VDC

### Use the Keypad to set the following options:

Supply Voltage - PULSE ENC VOLTS (S17)

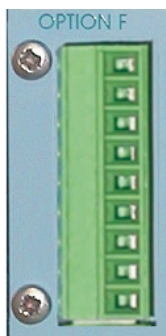
Number of lines per revolution - ENCODER LINES parameter (S18)

\* Encoder direction - ENCODER INVERT (S19)

\* Used to match the encoder direction to the motor direction. When TRUE, changes the sign of the measured speed and the direction of the position count. It is necessary to set up this parameter when in CLOSED-LOOP VEC mode, as the encoder direction must be correct for this mode to operate.

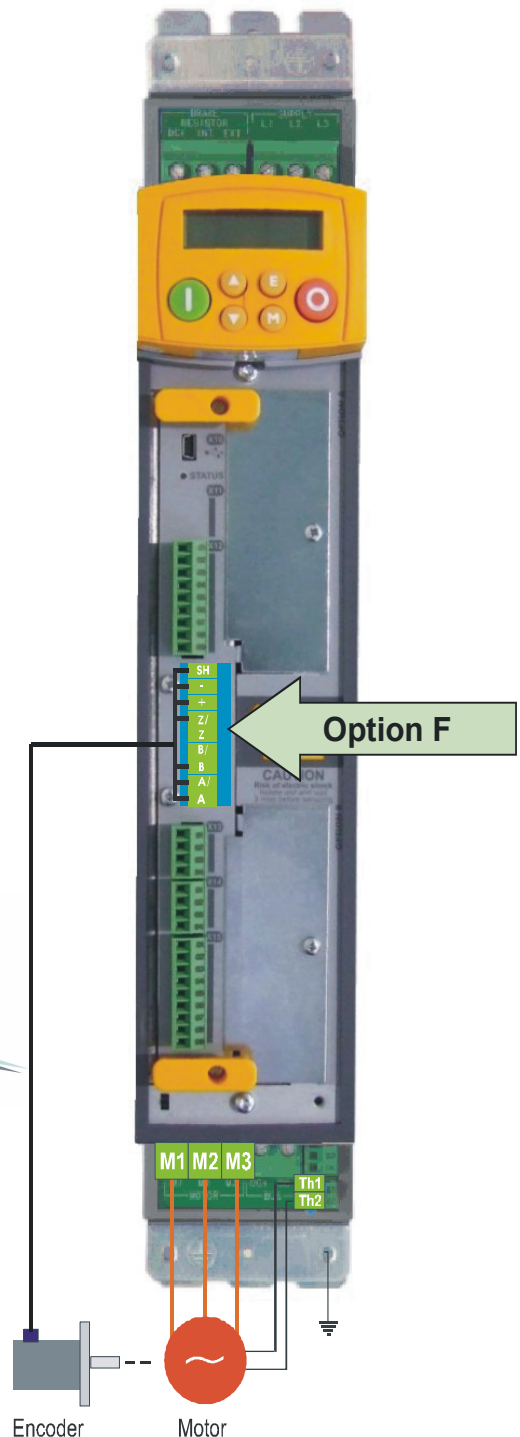
Using other types of encoders requires the DSE Configuration Tool and the setting of other parameters. Refer to the 890 Engineering Reference Manual for details of these parameters.

Use 3-pair or 4-pair, individually shielded encoder cable, Belden model 8777 or equivalent.



### OPTION F Terminal Block

- |    |            |
|----|------------|
| 01 | Shield     |
| 02 | Supply -   |
| 03 | Supply +   |
| 04 | Channel Z/ |
| 05 | Channel Z  |
| 06 | Channel B/ |
| 07 | Channel B  |
| 08 | Channel A/ |
| 09 | Channel A  |



# Drive Start-up

## Before Applying Power :

- Read the Safety section at the front of the QuickStart.
- Ensure that all local electric codes are met.
- Check for damage to equipment.
- Check for loose ends, clippings, filings, drilling swarf etc. lodged in the drive and system.
- Check all external wiring circuits of the system - power, control, motor and earth connections.
- Ensure that unexpected rotation of the motor in either direction will not result in damage, bodily harm or injury. Disconnect the load from the motor shaft, if possible.
- Check the state of the Motor Thermistor and Brake Resistor connectors. Check external run contacts are open. Check external speed setpoints are all at zero.
- Ensure that nobody is working on another part of the system which will be affected by powering up.
- Ensure that other equipment will not be adversely affected by powering up.
- Check motor stator connections are correctly wired for for Star or Delta as necessary for drive output voltage.

**If all connections have been checked, it is time to **POWER UP** the drive.**

# Drive Set-up

Refer to Appendix A if using the 6511 keypad supplied with the drive. Appendix B contains information about the 6901 keypad that displays menu and parameter names in English.

## Motor Data

Before attempting to set up the drive, you will need some motor information. This is found on the motor nameplate. The information you will need is listed below:

- Base Volts
- Base frequency
- Base RPM
- Full load amps
- No load amps (mag current)
- Connection (star or delta)

## Quick Setup Parameters

The following is a list of the Quick Setup parameters you must check before starting the drive. Set only the ones marked with “x” in the table below, under the intended mode of operation.

|     |                 |   | <u>V/Hz</u> | <u>SV</u> | <u>Vector</u> |
|-----|-----------------|---|-------------|-----------|---------------|
| S1  | Control Mode    | Select the intended operating mode              | x           | x         | x             |
| S2  | Max Speed       | Motor RPM at full process speed                 | x           | x         | x             |
| S7  | V/F shape       | Usually Linear. Choose fan curve only for fans  | x           |           |               |
| S9  | Motor Current   | Motor full load current from motor nameplate    | x           | x         | x             |
| S12 | Motor Base Freq | Motor nameplate frequency                       | x           | x         | x             |
| S13 | Motor Voltage   | Motor nameplate voltage                         | x           | x         | x             |
| S14 | Nameplate RPM   | Motor nameplate RPM                             | x           | x         | x             |
| S15 | Motor Poles     | <i>See Note</i>                                 |             | x         | x             |
| S17 | Pulse Enc Volts | set between 10-20V to match encoder             |             |           | x             |
| S18 | Encoder Lines   | Pulses per Revolution of encoder                |             |           | x             |
| S19 | Encoder Invert  | Changes polarity of encoder feedback            |             |           | x             |
| S20 | Autotune Enable | Drive will Autotune if started                  |             | x         | x             |
| S22 | Mac Current     | Enter the No-Load Amps from the motor nameplate | x           | x*        | x*            |

\* if performing a Stationary Autotune.

**NOTE** Some of the parameters are product code dependent, that is, they are different for each frame size and power rating. For example, the unit will be set for either 50Hz or 60Hz operation:

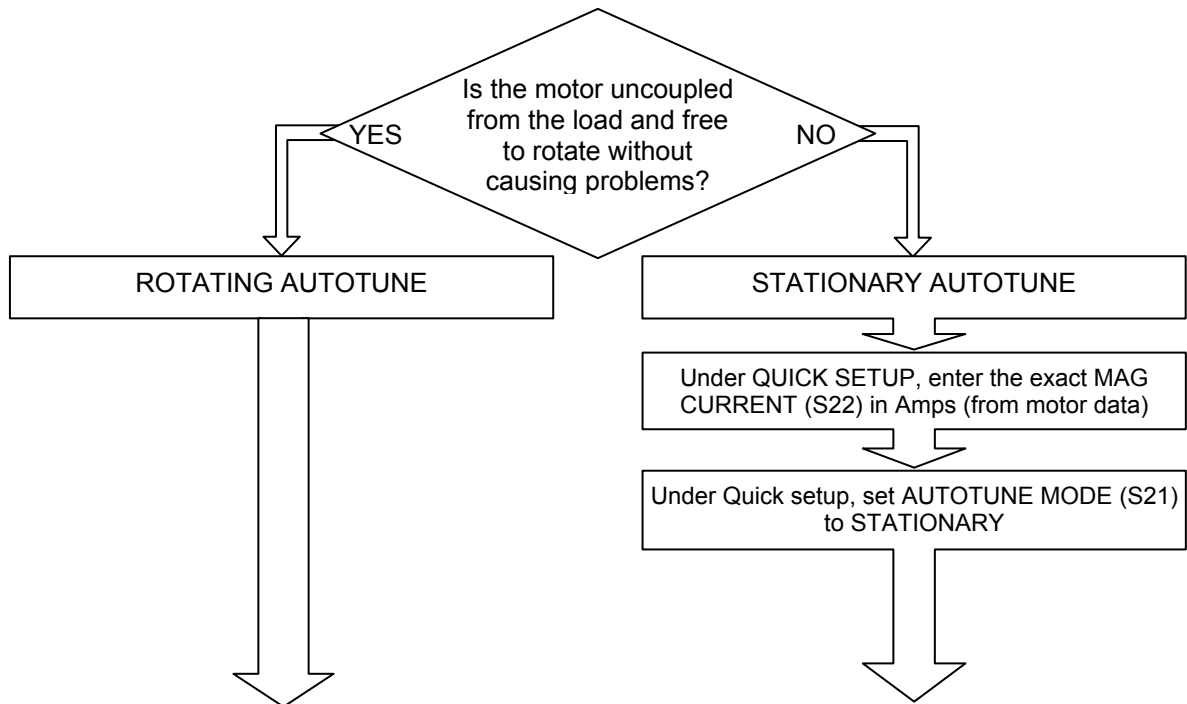
**Motor Poles for 60Hz** 2 poles = 3600 rpm, 4 poles = 1800 rpm, 6 poles = 1200 rpm

**Motor Poles for 50Hz** 2 poles = 3000 rpm, 4 poles = 1500 rpm, 6 poles = 1000 rpm

# Autotune

**This section is only for operating in Sensorless or Closed-loop Vector modes. If the drive is in V/Hz mode, Autotune is unnecessary and will not Enable.**

- Ensure that MAX SPEED is greater than NAMEPLATE RPM for a successful autotune.
- In the QUICK SETUP menu, set AUTOTUNE ENABLE (S20) to TRUE.



- On the 890SD keypad select LOCAL mode. Set the local setpoint, OP 1, to 0.0%.
- Press the green RUN button. The drive will begin autotuning. The drive will stop without errors if autotune is successful.
- Go to SYSTEM::SAVE CONFIG::APPLICATION and UP arrow to save your settings

## Running in Local

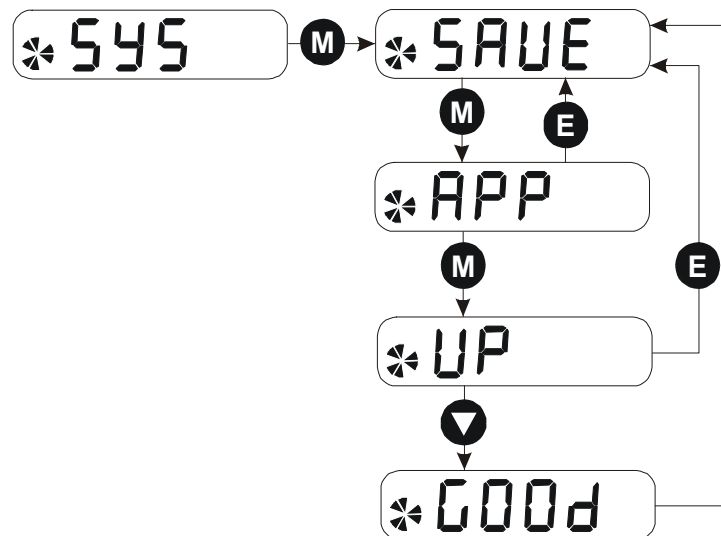
- On the 890SD keypad select LOCAL mode. The display will show the Local Setpoint : 0.0%
- Use the UP arrow to set a Local Setpoint, for example 20%.
- Press the green RUN button. The motor will accelerate to the desired speed and maintain it. Adjust RAMP ACCEL TIME (S3) in Quick Setup to the desired level.
- Press the red STOP button. The motor will decelerate to a stop. Adjust RAMP DECEL TIME (S4) in Quick Setup to desired level. If the drive trips on Overvoltage, extend the RAMP DECEL TIME or connect a braking resistor. Refer to the 890 Engineering Reference Manual.

Go to SYS::SAVE::APP and UP arrow to save your settings. Values are stored during power-down.

## Running in Remote

- On the 890SD keypad select REMOTE mode. The display will show the remote Setpoint : ?.?% (The value displayed depends on the external speed reference).
- Dial in a speed setpoint using the Speed potentiometer until the display reads 20%.
- Start the drive by closing the Start contact between terminal X14/03 and terminal X15/02. The motor will accelerate to the desired speed and maintain it. Adjust RAMP ACCEL TIME (S4) in Quick Setup to the desired level.
- Open the Start contact. The motor will decelerate to a stop. Adjust RAMP DECEL TIME (S4) in Quick Setup to desired level. If the drive trips on Overvoltage, extend the RAMP DECEL TIME or connect a braking resistor. Refer to the 890 Engineering Reference Manual..

Go to SYS::SAVE::APP and UP arrow to save your settings. Values are stored during power-down.





# Appendix A: Using the 6511 Keypad






The 6511 is the keypad that comes as standard with any 890 product. It is a one-line backlit LCD with units and symbols for different functions. It can be used to setup and configure the 890. It can also be used to operate the drive in Local mode from its Start and Stop buttons.

From power-up, the keypad displays the Software Version, and then times-out to show the Remote Setpoint, as shown opposite.




## To change Operating Mode:

You must be at the top of the MMI, showing the software version, before you can change between local and remote modes.

| Mode            | Action   |
|-----------------|--|
| Remote to Local | Hold the Stop key  down until <b>LOC</b> is displayed<br>  |
| Local to Remote | Hold the Stop key  down until <b>LOC</b> and  are removed and the software version is displayed<br> |

## To display the software version:

Press  repeatedly to display software version

## To Start in Local Mode:

Press 

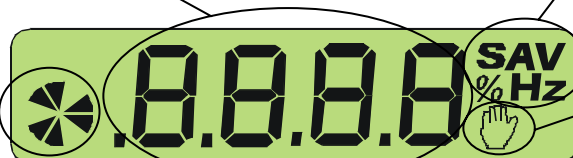
## To Stop in Local Mode:

Press 

Displays diagnostics, parameter and trip information

Displays the units for the value:  
**S** for seconds, **A** for current in Amps, **V** for voltage in Volts, **%** for percentage, **Hz** for frequency in Hertz

Indicates motor shaft direction



Indicates Local Mode (Remote Mode when not visible)

# The Menu Structure

The main menus are shown below. Each menu contains parameters.



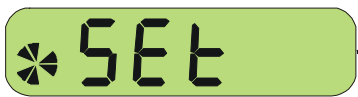
This is the power-up welcome screen. If a different screen appears, press E a few times to return to this screen



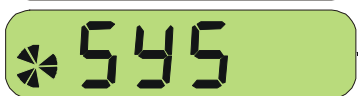
Press the M key to get to OPERATOR menu



DOWN arrow to get to the DIAGNOSTICS menu



DOWN arrow to get to the QUICK SETUP menu






DOWN arrow to get to the SYSTEM menu



**NOTE** Refer to the Engineering Reference Manual for a list of available parameters.


## How to Edit a Parameter

Press  to enter the SET::QUICKSETUP menu.

Scroll through the parameters using the  and  keys.

Press  to select a parameter for editing.

Increment/decrement the parameter value using the  and  keys.

Press  to exit the parameter.

# Appendix B: Using the 6901 Keypad

The 6901 keypad can be plugged into any 890 product. It is a two-line backlit LCD display with units and symbols. It can be used to setup and configure the 890 in plain language. It can also be used to operate the drive in Local mode from its Start and Stop buttons, Jog and reverse.



### To display the Software Version and Voltage Rating:

Press **E** repeatedly to display the Welcome Screen.

Press **M** to return to the Menus.

### To Start in Local Mode:

Press **I**.

### To Stop in Local Mode:

Press **O**.

SEQ and REF LEDs are On when in Local mode

|                   |                         |                                |                             |                         |
|-------------------|-------------------------|--------------------------------|-----------------------------|-------------------------|
| <b>Menus</b>      | <b>E</b> exit a menu    | <b>M</b> sub-menu or parameter | <b>▲</b> scroll up          | <b>▼</b> scroll down    |
| <b>Parameters</b> | <b>E</b> exit parameter | <b>M</b> make writable         | <b>▲</b> previous parameter | <b>▼</b> next parameter |
| <b>Edit</b>       | <b>E</b> stop editing   | <b>M</b> show PREF (hold)      | <b>▲</b> inc value          | <b>▼</b> dec value      |

### To change Operating Mode:

From power-up, the keypad displays the Software Version, and then times-out to show the Remote Setpoint.

| Mode            | Action   |
|-----------------|--|
| Remote to Local | Toggle between modes using the L/R key <b>L/R</b><br>SEQ and REF LEDs are On when in Local   |
| Local to Remote | Toggle between modes using the L/R key <b>L/R</b><br>SEQ and REF LEDs are Off when in Remote |

# The Menu Structure

The main menus are shown below. Each menu contains parameters.



**AC MOTOR DRIVE**  
15kW 400V 1.x



**OPERATOR**  
menu at level 1

Press the M key to get to the OPERATOR menu



**DIAGNOSTICS**  
menu at level 1

DOWN arrow to get to the DIAGNOSTICS menu



**QUICK SETUP**  
menu at level 1

DOWN arrow to get to the QUICK SETUP menu



**SETUP**  
menu at level 1

DOWN arrow to get to the SETUP menu -  
contains all the parameters



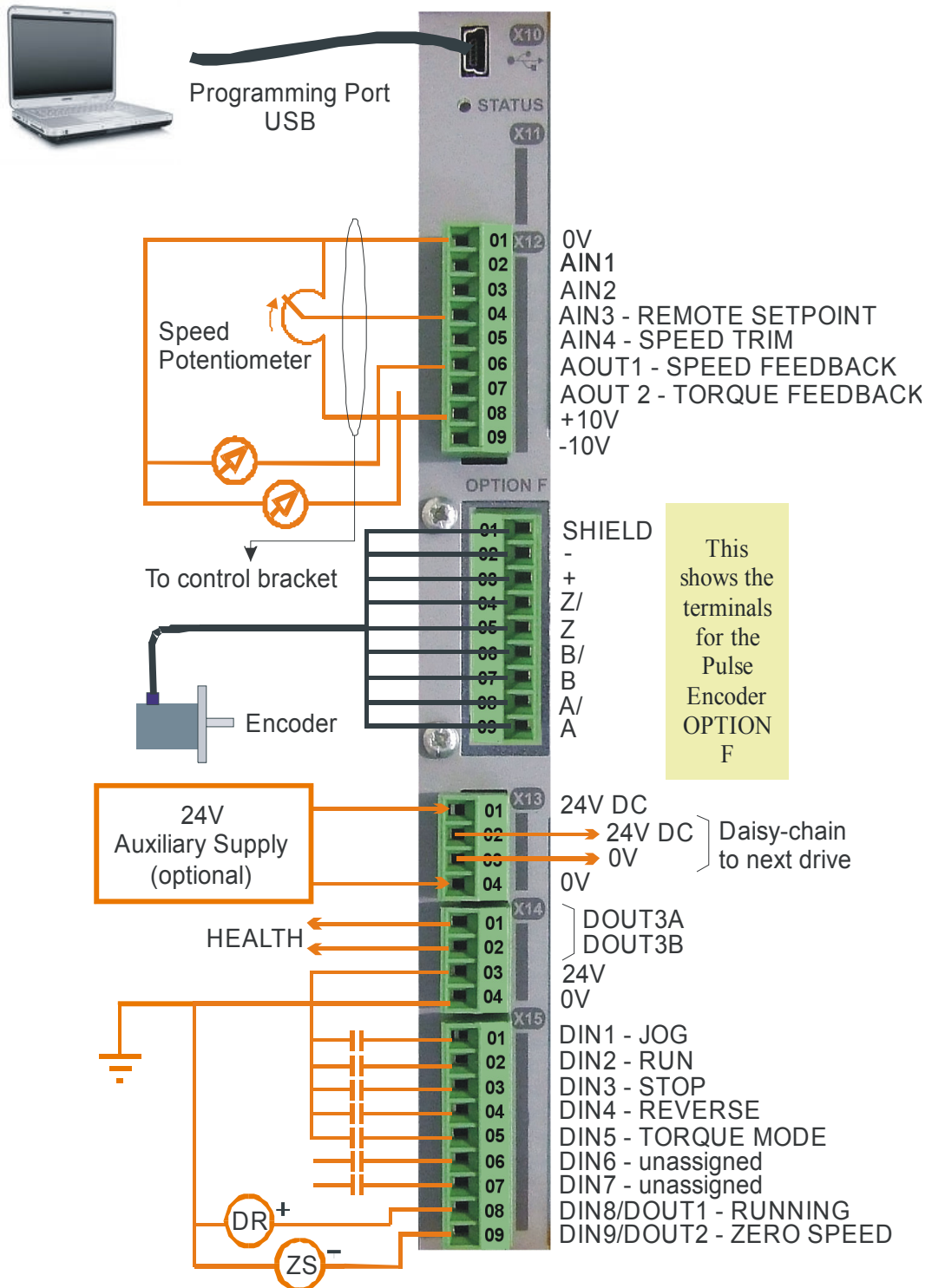
**SYSTEM**  
menu at level 1

DOWN arrow to get to the SYSTEM menu

**NOTE** Refer to the Engineering Reference Manual for a list of available parameters.

# Appendix C: Analog and Digital I/O

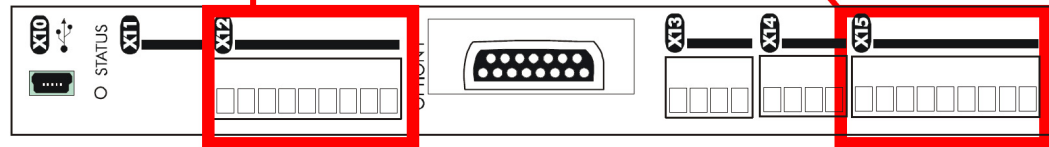
The terminal function names apply to the factory shipping configuration. These terminals may have different functions if the configuration has been modified using DSE.



# 890SD Control Terminals

The terminal function names apply to the factory shipping configuration. These terminals may have different functions if the configuration has been modified using DSE.

- Analog I/O connector is X12
- Analog I/O resolution is 12 bit plus sign
- Digital I/O connector is X15
- Digital I/O is 24VDC, sourced, active high



| Terminal           | Name       | Range                          | Description   |
|--------------------|------------|--------------------------------|---|
| <b>ANALOG I/O</b>  |            |                                |   |
| X12/01             | 0V         |                                | 0V reference for analog I/O   |
| X12/02             | AIN1       | 0-10V, ±10V                    | Analog Input 1<br>Configurable (default = diff I/P +)                       |
| X12/03             | AIN2       | 0-10V, ±10V                    | Analog Input 2<br>Configurable (default = diff I/P -)                       |
| X12/04             | AIN3       | ±10V, 0-10V,<br>0-20mA, 4-20mA | Analog Input 3<br>Configurable (default = remote setpoint I/P)              |
| X12/05             | AIN4       | ±10V, 0-10V,<br>0-20mA, 4-20mA | Analog Input 4<br>Configurable (default = speed trim I/P)                   |
| X12/06             | AOUT1      | ±10V<br>(10V=100%speed)        | Analog Output 1<br>Configurable (default = speed feedback O/P)              |
| X12/07             | AOUT2      | ±10V<br>(10V=200% torque)      | Analog Output 2<br>Configurable (default = torque feedback O/P)             |
| X12/08             | +10V REF   | +10V                           | 10V reference for analog i/o. Load 10mA maximum                             |
| X12/09             | -10V REF   | -10V                           | 10V reference for analog i/o. Load 10mA maximum                             |
| <b>DIGITAL I/O</b> |            |                                |   |
| X15/01             | DIN1       | 0 or 24V                       | Configurable Digital Input 1 (default = Jog)                                |
| X15/02             | DIN2       | 0 or 24V                       | Configurable Digital Input 2 (default = Run)                                |
| X15/03             | DIN3       | 0 or 24V                       | Configurable Digital Input 3 (default = Stop)                               |
| X15/04             | DIN4       | 0 or 24V                       | Configurable Digital Input 4 (default = Reverse)                            |
| X15/05             | DIN5       | 0 or 24V                       | Configurable Digital Input 5 (default = Torque mode)                        |
| X15/06             | DIN6       | 0 or 24V                       | Configurable Digital Input 6 (default = Unassigned)                         |
| X15/07             | DIN7       | 0 or 24V                       | Configurable Digital Input 7 (default = Unassigned)                         |
| X15/08             | DIN8/DOUT1 | 0 or 24V                       | Configurable Digital Input/output<br>(default : digital input = Running)    |
| X15/09             | DIN9/DOUT2 | 0 or 24V                       | Configurable Digital Input/output<br>(default : digital input = Zero Speed) |

# Appendix D: Electrical Ratings

## 890SD Standalone Drive

Input currents are listed at 230Vac 50Hz, 400Vac 50Hz, and 460Vac 60Hz. Motor power, input current and output current ratings must not be exceeded under steady state operating conditions. Vector Mode 150% overload for 60 seconds. Servo Mode 200% overload for 4 seconds.

### FRAME B Short circuit current rating of supply: 5000A.

| Model Number                      | 890SD/2/0003B | 890SD/2/0005B | 890SD/2/0007B | 890SD/2/0011B | 890SD/2/0016B  |
|-----------------------------------|---------------|---------------|---------------|---------------|----------------|
| Nominal Supply Voltage            | 230 Vac       |               |               |               |                |
| Motor Power                       | 0.55/0.75     | 1.1/1.5       | 1.5/2         | 2.2/3         | 4/5            |
| Input Current - Vector Mode       | 4.2           | 7.7           | 9.3           | 15.2          | 21.8           |
| Output Current - 3kHz Vector Mode | 3             | 5.5           | 7             | 11            | 16.5           |
| Output Current - 4kHz Servo Mode  | 2.2           | 4             | 6             | 8             | 12             |
| Minimum External Braking Resistor | 36            | 36            | 36            | 36            | 22             |
| Model Number                      | 890SD/5/0002B | 890SD/5/0003B | 890SD/5/0004B | 890SD/5/0006B | 890SD/5/0006B  |
| Nominal Supply Voltage            | 400 Vac       | 460-500 Vac   | 400 Vac       | 460-500 Vac   | 400 Vac        |
| Motor Power                       | 0.55kW        | 1.1kW         | 1.5kW         | 2.2kW         | 3Hp            |
| Input Current - Vector Mode       | 2.9           | 5             | 6.8           | 9.0           | 7.2            |
| Output Current - 3kHz Vector Mode | 2             | 3.5           | 4.5           | 6             | 5              |
| Output Current - 4kHz Servo Mode  | 1.5           | 2.5           | 3.5           | 4             | 4              |
| Minimum External Braking Resistor | 100           | 100           | 100           | 100           | 100            |
| Model Number                      | 890SD/5/0010B | 890SD/5/0012B | 890SD/5/0016B | 890SD/5/0016B | 890SD/5/S0016B |
| Nominal Supply Voltage            | 400 Vac       | 460-500 Vac   | 400 Vac       | 460-500 Vac   | 400 Vac        |
| Motor Power                       | 4kW           | 5Hp           | 7.5kW         | 10Hp          | 7.5kW          |
| Input Current - Vector Mode       | 14            | 11.1          | 16.5          | 18.7          | 23.4*          |
| Output Current - 3kHz Vector Mode | 10            | 8             | 12            | 14            | -              |
| Output Current - 4kHz Servo Mode  | 6             | 6             | 9             | 10            | 14             |
| Minimum External Braking Resistor | 100           | 100           | 56            | 56            | 56             |

\* Values are for "Input Current - Servo Mode".

## 890SD Standalone Drive

Input currents are listed at 230Vac 50Hz, 400Vac 50Hz, and 460Vac 60Hz. Motor power, input current and output current ratings must not be exceeded under steady state operating conditions. Vector Mode 150% overload for 60 seconds. Servo Mode 200% overload for 4 seconds.

### FRAME C Short circuit current rating of supply: 10000A.

| Model Number                      | 890SD/2/0024C | 890SD/2/0030C | 890SD/5/0024C | 890SD/5/0030C | 890SD/5/0030C | 890SD/5/S030C |
|-----------------------------------|---------------|---------------|---------------|---------------|---------------|---------------|
| Nominal Supply Voltage            | Vac           | 230           | 230           | 400           | 460-500       | 400           |
| Motor Power                       | kW/HP         | 5.5/7.5       | 7.5/10        | 11kW          | 15HP          | 15kW          |
| Input Current - Vector Mode       | A             | 31            | 40            | 32            | 27            | 40            |
| Output Current - 3kHz Vector Mode | A             | 24            | 30            | 24            | 24            | 30            |
| Output Current - 4kHz Servo Mode  | A             | 24            | 30            | 20            | 20            | 25            |
| Minimum External Braking Resistor | Ω             | 15            | 12            | 36            | 36            | 30            |

### FRAME D Short circuit current rating of supply: 10000A.

| Model Number                      | 890SD/5/0039D | 890SD/5/0045D | 890SD/5/0059D |
|-----------------------------------|---------------|---------------|---------------|
| Nominal Supply Voltage            | Vdc           | 460-500       | 460-500       |
| Motor Power                       | kW/HP         | 18.5kW        | 22kW          |
| Input Current - Vector Mode       | A             | 42            | 50            |
| Output Current - 3kHz Vector Mode | A             | 39            | 45            |
| Output Current - 4kHz Servo Mode  | A             | 35            | 38            |
| Minimum External Braking Resistor | Ω             | 20            | 20            |