

8903/FA

FireWire IEEE 1394a

Communications Interface

Technical Manual

HA469265U001 Issue 4

Compatible with Version 1.x Software

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WARRANTY

Parker SSD Drives warrants the goods against defects in design, materials and workmanship for the period of 12 months from the date of delivery on the terms detailed in Parker SSD Drives Standard Conditions of Sale IA058393C.

Parker SSD Drives reserves the right to change the content and product specification without notice.

Safety Information



WARNING!

During commissioning, remove the fuses (or trip the circuit breaker) on your 3-phase supply.
Make sure the power is OFF, and that it cannot be switched on accidentally whilst you are working.

REFER TO YOUR MAIN PRODUCT MANUAL FOR SPECIFIC SAFETY INFORMATION ABOUT THE DEVICE YOU ARE CONTROLLING

IMPORTANT: Please read this information BEFORE installing the equipment.

Intended Users

This manual is to be made available to all persons who are required to install, configure or service equipment described herein, or any other associated operation.

The information given is intended to highlight safety issues, EMC considerations, and to enable the user to obtain maximum benefit from the equipment.

Application Area

The equipment described is intended for industrial motor speed control.

Personnel

Installation, operation and maintenance of the equipment should be carried out by qualified personnel. A qualified person is someone who is technically competent and familiar with all safety information and established safety practices; with the installation process, operation and maintenance of this equipment; and with all the hazards involved.

Safety

All control and signal terminals are SELV, i.e. protected by double insulation.

EMC

In a domestic environment this product may cause radio interference in which case the user may be required to take adequate counter-measures.

This equipment contains electrostatic discharge (ESD) sensitive parts. Observe static control precautions when handling, installing and servicing this product.

Safety Information



CAUTION!

At any time, there may be a loss of motor control and separate/independent application measures should be taken to ensure that such loss of motor control cannot present a safety hazard.

RISK ASSESSMENT

Under fault conditions, power loss or unintended operating conditions, the drive may not operate as intended. In particular:

- Stored energy might not discharge to safe levels as quickly as suggested, and can still be present even though the drive appears to be switched off
- The motor's direction of rotation might not be controlled
- The motor speed might not be controlled
- The motor might be energised

A drive is a component within a drive system that may influence its operation or effects under a fault condition. Consideration must be given to:

- Stored energy
- Supply disconnects
- Sequencing logic
- Unintended operation

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FIREWIRE COMMUNICATIONS INTERFACE

Introduction

This manual describes the Parker SSD Drives' FireWire® Communications Interface Option (TechCard).

Note: FireWire is also known as IEEE1394 and is a high speed peer-to-peer serial bus.

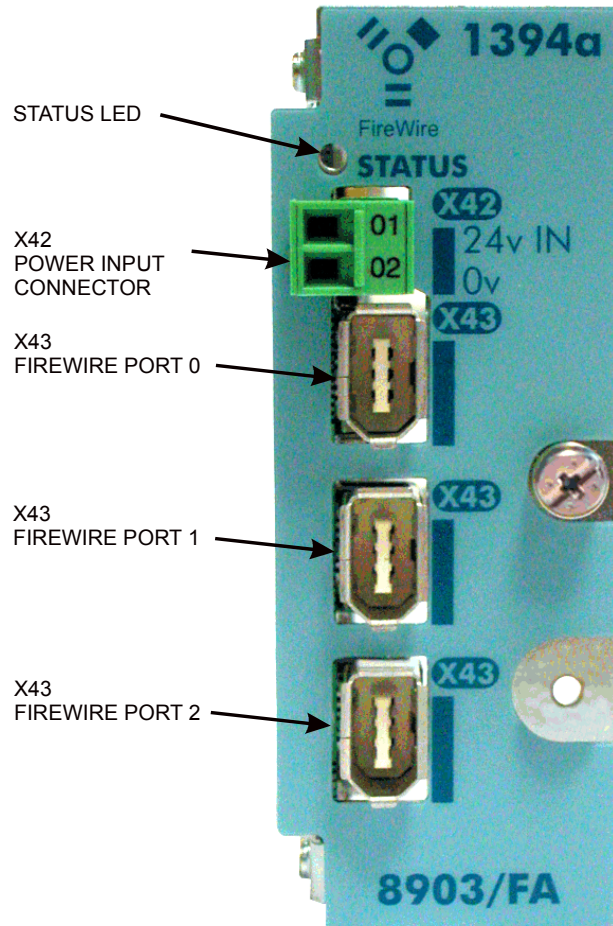


Figure 1. Front of the 8903/FA FireWire Communications Interface Option (TechCard)

Part Number

The part number for the FireWire Communications Interface Option is :

8903/FA

8903/FA/FF (indicates a factory-fitted option)

Used On

The TechCard can be used on 890 drives with the following Product Codes:

890SD/..	890SD Standalone Drive
890CD/..	890CD Common Bus Drive

Refer to the 890 Engineering Reference Manual, Appendix E for Product Code details.

Recommended Spare Parts

We recommend that you keep one TechCard as a spare to reduce down-time.

2 Installation

WARNING!
Disconnect all sources of power before attempting installation.

Caution

This TechCard contains ESD (Electrostatic Discharge) sensitive parts. Observe static control precautions when handling, installing and servicing this option.

To Remove the Control Board

1. Remove the blank covers, each secured by a single screw (1), that fit over the TechCard slots.
2. Undo the top and bottom captive screws in the blue handles of the Control Board (2).
3. Pull gently on the handles and slide the Control Board (2) out of the drive.

Note: Save the blank cover and screw for future use. The drive should not be operated without a TechCard or blank cover. When fitted, these maintain the drive's IP20 rating.

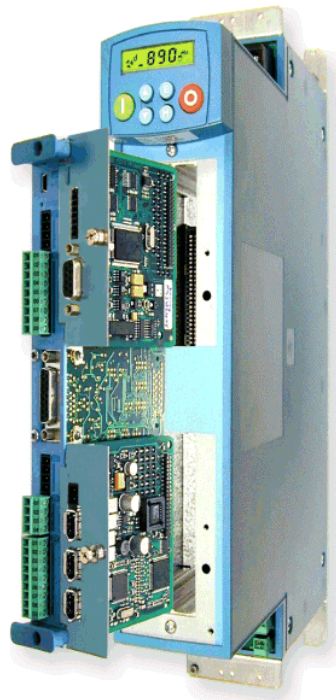


Figure 2. 890 showing Control Board withdrawn with Options fitted



Figure 3. Front of 890 drive showing Control Board fitted

Fitting the TechCard

The TechCard fits on to the Control Board.

1. Insert the connector into the TechCard as shown. The legs of the connector will protrude through into the connector on the other side of the TechCard.
2. Press the assembly into the **BOTTOM** connector (adjacent to terminals X13, X14 and X15) on the Control Board. Ensure that the front panel of the TechCard overlaps the front of the Control Board. Ease the connector at the TechCard so that the two pcb's are parallel when viewed on edge.

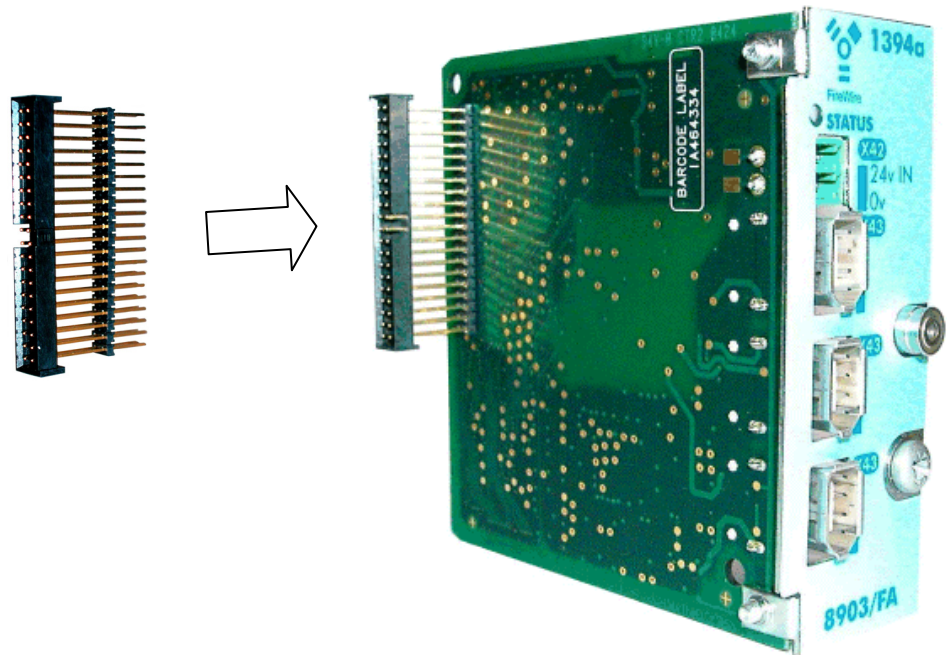


Figure 4. Fitting the connector to the TechCard

Re-fitting the Control Board

1. Slide the board into the drive, engaging the edges of the boards into the slots. Push until the back edge of the Control Board pcb locates with the connectors in the drive.
2. Tighten in position using the top and bottom screws in the blue handles of the Control Board.
3. Screw the TechCard in position using the captive screw on the front of the Option.

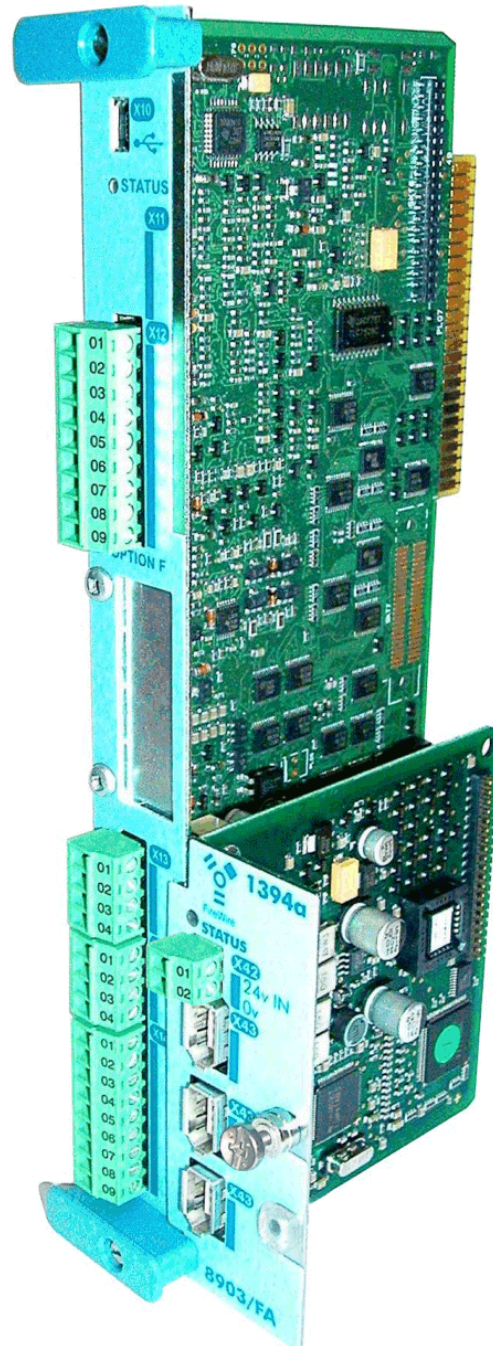


Figure 5. 890 Control Board with FireWire Communications Option fitted

Wiring the System

Terminology

Node :	Any single piece of IEEE1394 connected apparatus
Bus :	The network of interconnected IEEE1394 nodes
Hop :	Any single IEEE1394 interconnecting cable
Lonely :	No other active nodes detected

Powering the Node

IMPORTANT: DO NOT power the TechCard using the drive's 24V.

The IEEE1394 bus requires a **separate, floating** 24Vdc (12-24Vdc) supply connected to the Power Input Connector, terminal X42.

As a guide, each node may take up to 20mA at 24V from this supply. A node will draw more current at lower supply voltages, for example, a node may draw up to 40mA using a 12V supply.

Supply 24Vdc to one of the nodes on the bus. The 24Vdc is transferred to other nodes on the bus via the IEEE1394 cable.

Pin 01 = 24V
Pin 02 = 0V

If you do power more than one node on the same bus (for instance, one supply in each of two enclosures allowing for one of the enclosures to be isolated yet maintaining the bus), the supplies must again be **separate, floating** supplies.

Connect the 24V supply to the X42 terminal block using twisted pair cable.

Connecting the Nodes

Use an IEEE 1394a cable to connect two nodes together. These cables are considered electrically sensitive. In electrically noisy environments, FireWire messages may be corrupted. If this occurs, the system will automatically recover by restarting the communications. This process is called a Bus Reset and can take up to 0.5 seconds to complete. During this time data will not be transferred by the bus.

To avoid Bus Resets, keep electrically noisy and sensitive cables apart. Pay particular attention to screening and earthing of motor cables. Where necessary, sensitive cables should cross noisy cables at 90° to minimise capacitive coupling.

(The occurrence and frequency of Bus Resets can be monitored from the keypad).

The quality of RF earthing is important when using FireWire systems. In noisy environments, it is recommended that each drive front plate is strapped to an adjacent drive using a copper braid, to ensure a low impedance path for RF signals.

If some drives are mounted remotely, it is recommended that the FireWire cable between the drives is fitted with a ferrite RF absorption clamp (SSD Part Number : DJ467799).

We can supply the following recommended cables:

SSD Part Number	Cable Length
CM469189U002	0.2m
CM469189U003	0.28m
CM469189U010	1m
CM469189U045	4.5m
CM469189U100	10m

If using 10m cables, note that an additional limitation applies: the cable length limit between the two most distant nodes on the network is 72m. 10m cables should be used sparingly, and short (1m) cables should be used wherever possible to ensure this limit is not exceeded. See "Extenders" below.

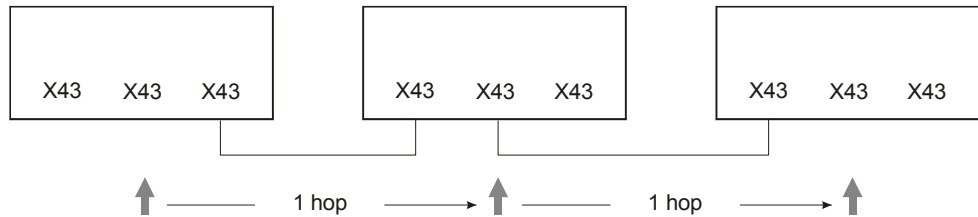
6

Each port is interchangeable – any message transmitted by the node exits all three ports. Any message received on one port is repeated on the other two ports.

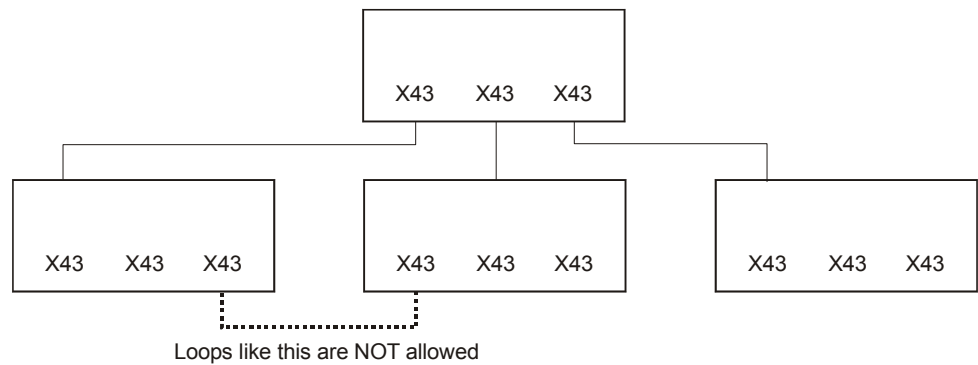
Nodes can be connected in a Daisy Chain or a Tree configuration but loops are not allowed.

The maximum number of hops between the most distant nodes on the network is 16, so for 17 or more nodes a Tree is essential. The maximum number of nodes is 63. Refer to Figure 6 on next page.

Note: The network power draw is approximately 20mA per node at 24V, approximately 40mA at 12V. Note that 63 nodes at 24V (20mA per) is 1.26A total. The power system has thermally self-resetting fuses for 1.5A. So, at 12V it is not possible to wire for more than 37 nodes reliably.



Daisy Chain Configuration



Tree Configuration

Extenders

If any hop needs to be longer than 10m, then an extender is required to repeat the bus over CAT5 cable or optical fibre. There are commercially available units such as:

www.fwdepot.com ...	FW2UTP-01	1x IEEE1394a port, 1xRJ45 CAT5 port
	FW2UTP-02A	1x IEEE1394a port, 2xRJ45 CAT5 port
	FW2UTP-02B	1x IEEE1394a port, 2xRJ45 CAT5 port

Any 2 of the above can be used with a CAT5 crossover cable of up to 100m.

www.newnex.com ... FireNex-MX (TM) 2xIEEE1394a ports, 1x optical duplex LC port

Two of the above can be used with 100m of LC to LC ,62.5125um, multi-mode optical cable.

DRIVE-DRIVE	HOPS
1	12
1	13
1	14
1	17
1	18
25	37
36	47

EXAMPLE 4 RACK
47 DRIVE NETWORK

NOTES

1. MAXIMUM NUMBER OF HOPS, OR CABLES BETWEEN ANY TWO NODES, MUST BE <=16.
2. 48 DRIVES WOULD VIOLATE WITH 17 HOP UNLESS MORE BRANCHING AT A LOWER LEVEL WAS DONE, I.E. MORE SMALLER RACKS, OR BREAKING RACKS INTO MULTIPLE BRANCHES.

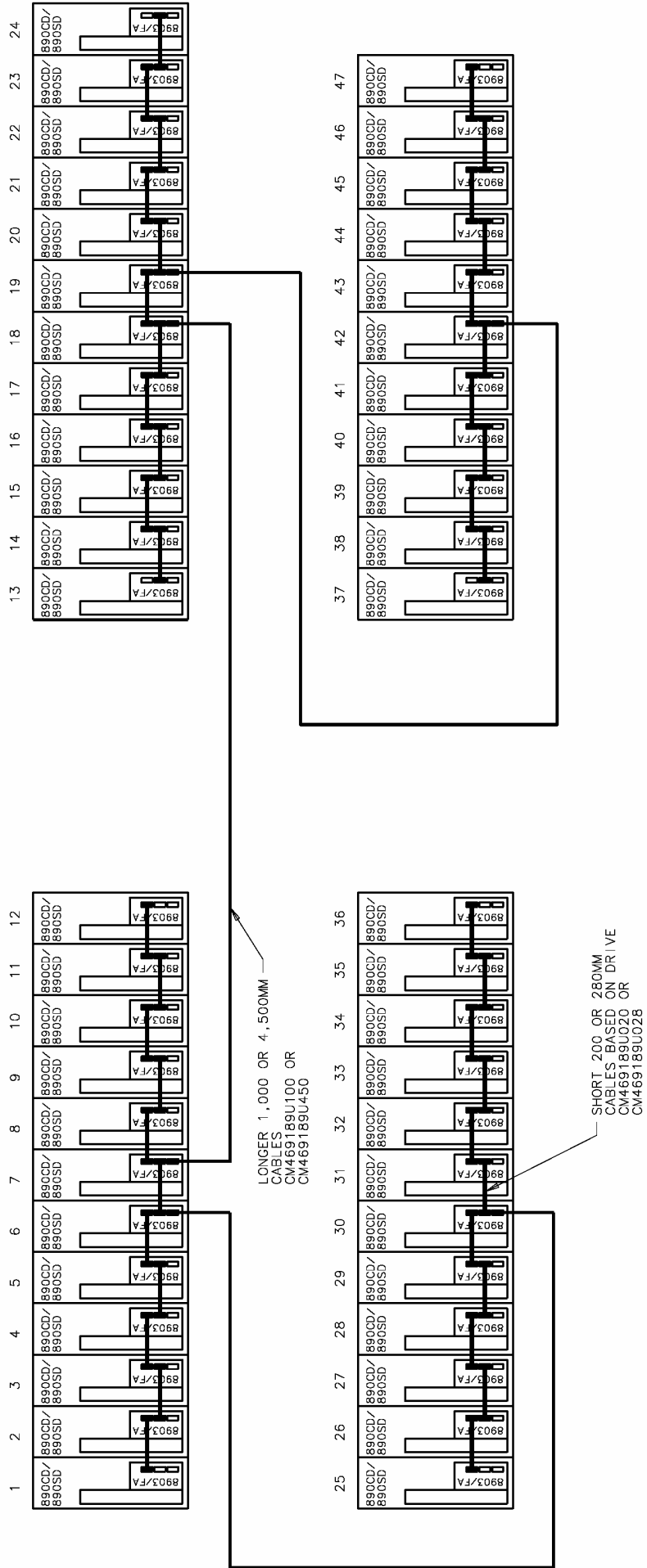


Figure 6. Example 4 Rack, 47 Drive Network

Initial Set-up

Configuring the 890 Drive

All drives in the system MUST be fitted with a FireWire TechCard that is wired correctly.

The FireWire TechCard is plug-and-play, requires no setting-up, and can be used in the following ways:

1. The Drive may exchange data with other Drives using Network inputs and outputs configured using DSE 890.
2. **DSE 890** : use FireWire to connect DSE 890 to all drives in the system.
3. **Peer-To-Peer** : use FireWire to link drive parameters.
4. **Virtual Axis** : use FireWire to broadcast synchronised information to all drives on the system (e.g. a shaftless printing application).

You can use the diagnostics provided in the FIREWIRE block to see your system at work.

FIREWIRE

SETUP::COMMS::FIREWIRE

The FireWire block parameterises FireWire communications, providing a series of diagnostics. There are no user settable parameters in this block.





Parameter Descriptions

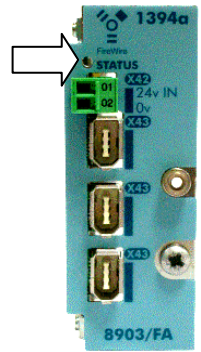
OWN ID	<i>PREF: 117.01</i>	<i>Default: 99</i>	<i>Range: —.</i>
FireWire network ID of the drive. This is the physical address, not the net address, as declared as part of the DSE Configuration. Note that this network ID can change after a Bus Reset.			
IRM ID	<i>PREF: 117.02</i>	<i>Default: 99</i>	<i>Range: —.</i>
FireWire network ID of the drive acting as the Isochronous Resource Manager. The IRM ID can change after a Bus Reset.			
NUMBER OF NODES	<i>PREF: 117.03</i>	<i>Default: 0</i>	<i>Range: —.</i>
Total number of FireWire Nodes connected to the network..			
CYCLE TIMER	<i>PREF: 117.04</i>	<i>Default: 0</i>	<i>Range: —.</i>
Timer which should be synchronised across the FireWire network.			
BUS RESETS	<i>PREF: 117.05</i>	<i>Default: 0</i>	<i>Range: —.</i>
Number of times the FireWire bus has reset since power-on.			
BAD MESSAGES	<i>PREF: 117.13</i>	<i>Default: 0</i>	<i>Range: —.</i>
Number of incoming Firewire messages that are received malformed. An incrementing value may indicate that the Firewire cabling needs attention.			
MISSED TX ACKS	<i>PREF: 117.14</i>	<i>Default: 0</i>	<i>Range: —.</i>
Number of outgoing Firewire messages that are not acknowledged. An incrementing value may indicate that the Firewire cabling needs attention.			
MCAP ADVERTS	<i>PREF: 117.06</i>	<i>Default: 0</i>	<i>Range: —.</i>
Count of Multicast Advertisements received by this node.			
MAX HOPS	<i>PREF: 117.07</i>	<i>Default: 0</i>	<i>Range: —.</i>
Maximum number of cable hops between the two most distant nodes on the network.			
OFFSET (40.69ns)	<i>PREF: 117.08</i>	<i>Default: 0</i>	<i>Range: —.</i>
Time delay between this node and the node hosting the Cycle Time Master.			

The DSE 890 Configuration Tool is Parker SSD Drives' Windows-based block programming software and is supplied with each 890 drive.

Status LED Indications

The Status LED on the TechCard indicates the following states:

Flash Sequence	Bus State
 50-50 OFF-RED	No Bus Power
 100 AMBER	Bus Reset
 50-50 OFF-GREEN	Bus Power On, only drive
 5-95 OFF-GREEN	Bus Running, multiple drives



Disposal

This product contains materials which are consignable waste under the Special Waste Regulations 1996 which complies with the EC Hazardous Waste Directive - Directive 91/689/EEC.

We recommend you dispose of the appropriate materials in accordance with the valid environmental control laws. The following table shows which materials can be recycled and which have to be disposed of in a special way.


Material	Recycle	Disposal
metal	yes	no
plastics material	yes	no
printed circuit board	no	yes

The printed circuit board should be disposed of in one of two ways:

1. High temperature incineration (minimum temperature 1200°C) by an incinerator authorised under parts A or B of the Environmental Protection Act
2. Disposal in an engineered land fill site that is licensed to take aluminium electrolytic capacitors. Do not dispose of in a land fill site set aside for domestic waste.

Packaging

During transport our products are protected by suitable packaging. This is entirely environmentally compatible and should be taken for central disposal as secondary raw material.

ISS.	MODIFICATION	ECN No.	DATE	DRAWN	CHK'D
1	Initial Issue (HA469265U001)	17320	14/04/05	CM	AFL
2	RF earthing details added - page 5	19213	10/02/06	CM	AFL
3	Changes to parameter details - page 8. Company name change	19768	09/01/07	CM	KJ
4	Company name change	19591	06/08/07	CM	KJ
FIRST USED ON		MODIFICATION RECORD 8903/FA FireWire Communications Interface			
		DRAWING NUMBER ZZ469265C001			SHT. 1 OF 1