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# HTTL Speed Feedback Option

Technical Manual

HA467152U001 Issue 6

Compatible with Version 1.x Software - 690+  
Compatible with Version 5.x Software - 605C

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# Safety Information



Please read this information **BEFORE** installing the equipment.

## **Intended Users**

This manual is to be made available to all persons who are required to install, configure or service equipment described herein, or any other associated operation.

The information given is intended to highlight safety issues, and to enable the user to obtain maximum benefit from the equipment.

## **Application Area**

The equipment described is intended for industrial motor speed control utilising AC/DC induction or synchronous machines.

## **Personnel**

Installation, operation and maintenance of the equipment should be carried out by qualified personnel. A qualified person is someone who is technically competent and familiar with all safety information and established safety practices; with the installation process, operation and maintenance of this equipment; and with all the hazards involved.

**REFER TO YOUR MAIN PRODUCT MANUAL FOR SPECIFIC SAFETY INFORMATION ABOUT THE DEVICE YOU ARE CONTROLLING**



# Contents

Contents

Page

<b>HTTL SPEED FEEDBACK OPTION</b>	<b>1</b>
<b>Description</b> .....	<b>1</b>
• <i>Features</i> .....	1
• <i>Used On</i> .....	1
• <i>Specifications</i> .....	1
Recommended Spare Parts .....	1
<b>Installation</b> .....	<b>2</b>
Wiring the System : 605C, 690+ Frames C-K .....	2
• <i>DIP Switch Settings</i> .....	3
• <i>Terminal Block (TB1) Connections</i> .....	3
• <i>Understanding the LED Indications</i> .....	4
Wiring the System : 690+ Frame B .....	4
• <i>DIP Switch Settings</i> .....	5
• <i>Terminal Block (TB1) Connections</i> .....	5
<b>Initial Set-up</b> .....	<b>6</b>
Configuring the 605C Inverter .....	6
Configuring the 690+ Inverter.....	8
<b>SSD Drives Approved Encoders</b> .....	<b>9</b>



# HTTL SPEED FEEDBACK OPTION

## Description

The HTTL Speed Feedback Option allows incremental encoders to be connected directly to the motor controller to provide highly accurate speed feedback measurement.

### Features

The option has the following features:

- Contains up to four optically isolated differential inputs on channels A, B, M and H
- Decoding logic to interface the encoder to the microprocessor
- Supplies variable voltage, isolated encoder power supply

### Used On

The HTTL Speed Feedback Option is provided in two forms:

1. Technology Box -for use with the 605C Inverter and 690+ Frames C-K Inverter
2. Speed Feedback Board - for use with the 690+ Frame B

### Specifications

	Technology Box	Speed Feedback Board
Maximum Pulse Rate	250kHz	250kHz
Receiver Current	≤10mA per channel	≤10mA per channel
Input Format	Two channels in quadrature, clock/dir or clock only	Two channels in quadrature, clock/dir or clock only
Phase Displacement	>1 $\mu$ s	>1 $\mu$ s
Input Voltage	10 - 30V differential recommended, or single-ended	10 - 30V differential recommended, or single-ended
Encoder Supply	Maximum load = 200mA or 2W, whichever is smaller. Voltage adjustable approximately 10-20V by firmware	Maximum load = 200mA or 2W, whichever is smaller. Voltage adjustable approximately 10-20V by firmware
Terminal Wire Size (maximum)	16 AWG	16 AWG
Terminal Tightening Torque	0.4Nm (3.5 pound-inches)	0.2Nm (1.75 pound-inches)

### Recommended Spare Parts

We recommend that you keep one option as a spare to reduce down-time.

# 2

## Installation

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### **WARNING!**

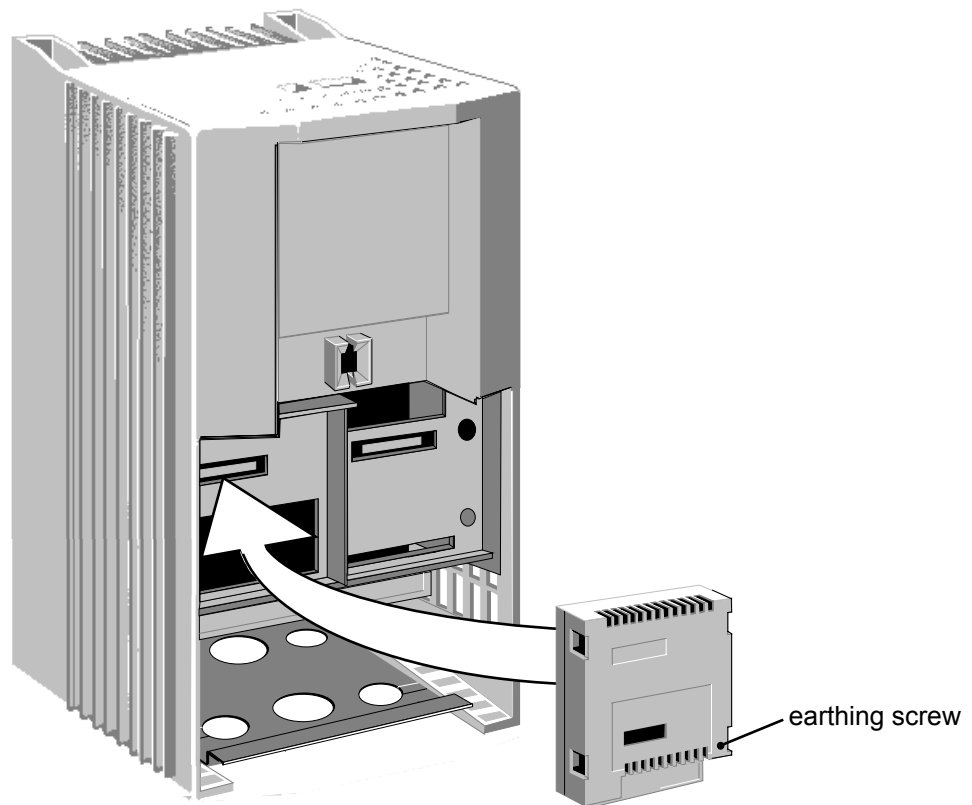
Disconnect all sources of power before attempting installation. Injury or death could result from unintended actuation of controlled equipment.

### **Caution**

This option contains ESD (Electrostatic Discharge) sensitive parts. Observe static control precautions when handling, installing and servicing this option.

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### **Wiring the System : 605C, 690+ Frames C-K**



**Figure 1 Installing the HTTL Speed Feedback Technology Box Option (605C illustrated)**

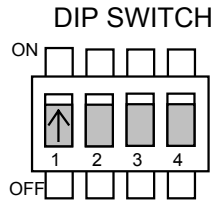
1. Unpack and handle the Option using correct static safety procedures.
2. Remove the inverter terminal cover and securing screws.
3. Carefully plug the Option into the left-hand port (as illustrated above) ensuring correct alignment of the connector and tighten the earthing screw. You can operate the Inverter with the Speed Feedback and/or a Communications Technology Box, but you **cannot** use two options of the same kind.



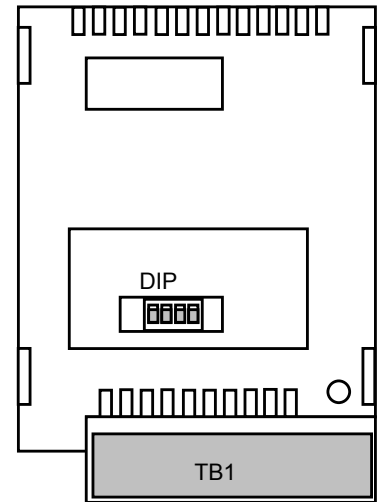
### DIP Switch Settings

The DIP switch can be seen through the casing of the HTTL Speed Feedback Technology Box.

The switch settings control the following inputs:



Input Threshold				
Switch Number	1	2	3	4
Input Controlled	H	A	B	M
3V±1	On	On	On	On
8V±1	Off	Off	Off	Off



Usually the switches will be set to give a threshold of 3V when using a differential encoder, and to 8V when using a single-ended encoder. (Factory default is with switches 1 & 2 set in the ON position - 3V).

### Terminal Block (TB1) Connections

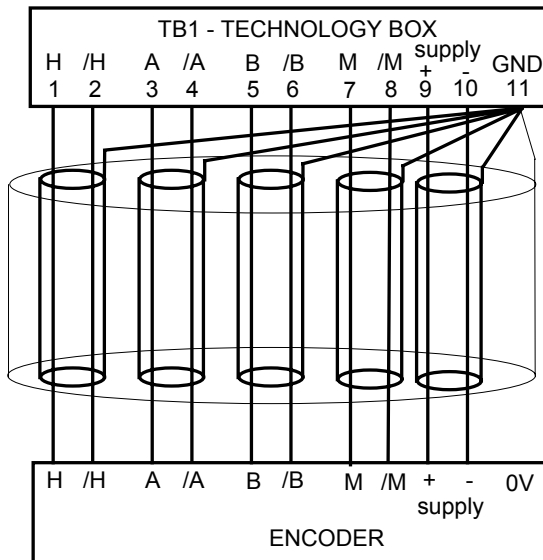


Figure 3 Differential Encoder Outputs

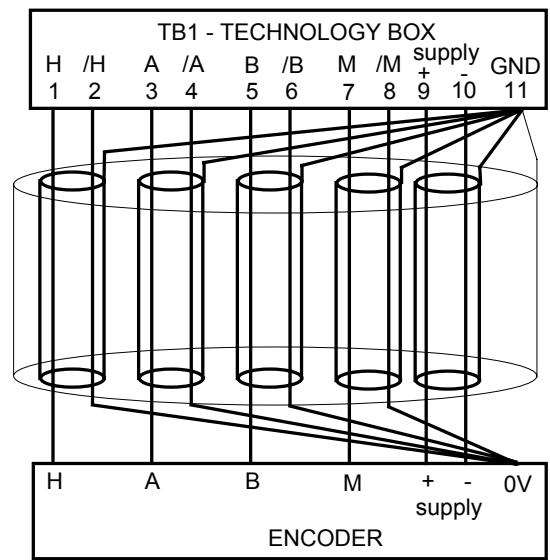


Figure 2 Single-Ended Encoder Outputs

For correct operation, A, /A, B and /B **must** be connected as shown. If any is left unconnected, the HTTL speed feedback technology box will not operate.

**Note:** The M and H inputs are not normally connected - these are for use with future versions of drive software.

*M:* For connection to the once-per-revolution marker output from the encoder to verify correct operation of the encoder.

*H:* For where the encoder has provision for a 'health' output.

Take special care wiring the encoders to the option due to the low level of the signals.

All wiring to the HTTL Speed Feedback Technology Box should be made in screened cable. Use cable with an overall screen and a screen over each individual pair. To ensure compliance with the EMC Directive the overall cable screen should be connected to the encoder body and to the terminal block, pin 11.

*Recommended cable (pairs individually screened):*

Belden equivalent 8777  
SSD Drives Part Number CM052666

## Understanding the LED Indications

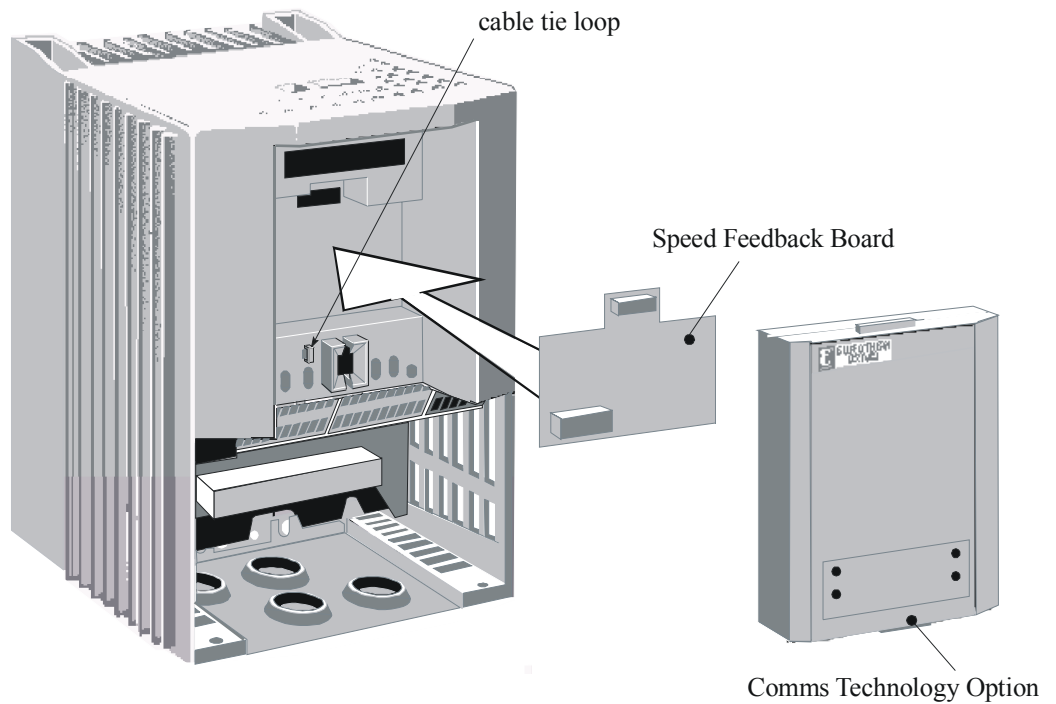
### Module LED

In normal operation this LED will be ON. If it fails to come on within 10 seconds after power-up check that the Technology Box is correctly installed.

### Encoder LED

This will indicate the status of the Health inputs, pins 1 and 2 on future versions of drive software. If the voltage across pins 1 and 2 exceeds the Minimum Differential Input Voltage set by the DIP switch, the Encoder LED will be ON (pin 1 is positive with respect to pin 2).

## Wiring the System : 690+ Frame B



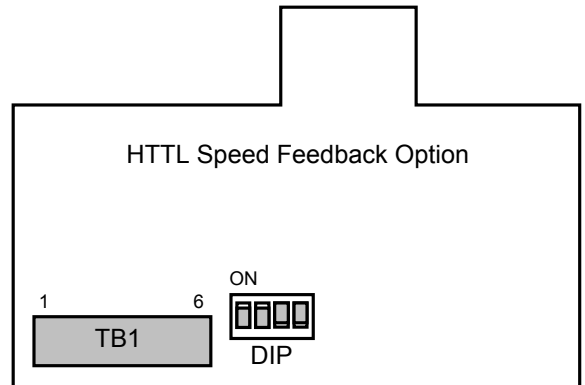
**Figure 4 The HTTL Speed Feedback Board fitted to 690+ Frame B**

The option is factory-fitted using correct static safety procedures. The cable tie loop is used to secure the connecting cable so that it doesn't obstruct the LED light pipes used by the Comms Technology Option.

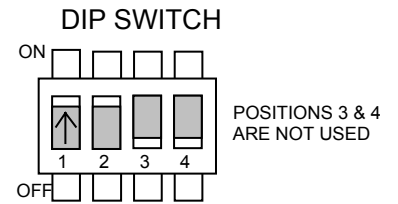
### DIP Switch Settings

The DIP switch settings control the following inputs:

Input Threshold		
Switch Number	1	2
Input Controlled	A	B
3V±1	On	On
8V±1	Off	Off



Usually the switches will be set to give a threshold of 3V when using a differential encoder (as shown), and to 8V when using a single-ended encoder. (Factory default is with switches 1 & 2 set in the ON position - 3V).



### Terminal Block (TB1) Connections

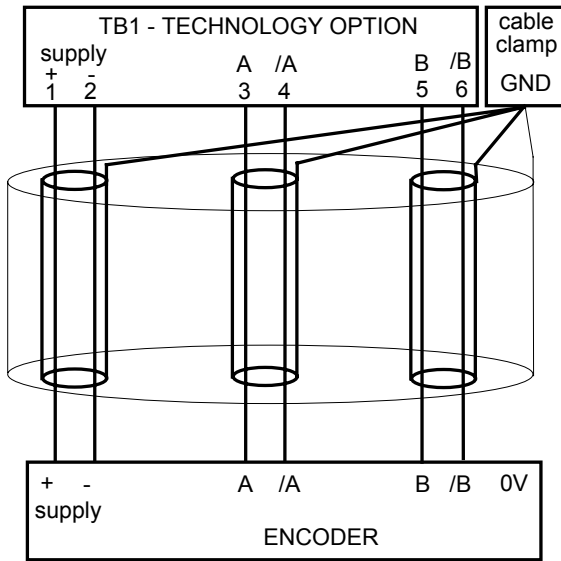


Figure 5 Differential Encoder Outputs

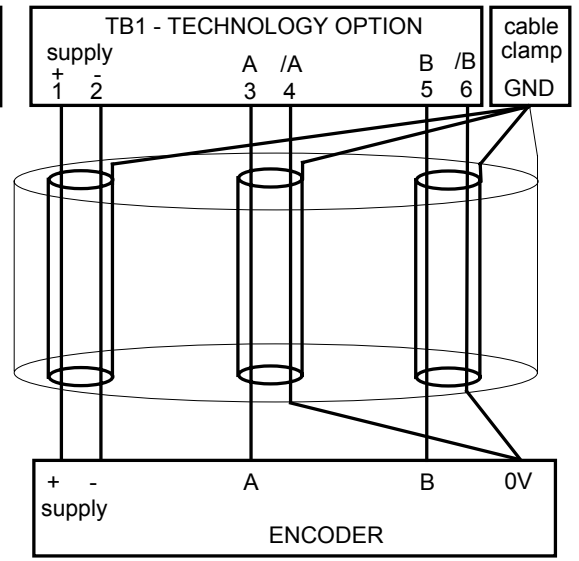


Figure 6 Single-Ended Encoder Outputs

**Note:** The GND connection shown above is the screen connection, some encoder manufacturers use a different terminology.

For correct operation, A, /A, B and /B **must** be connected as shown. If any is left unconnected, the HTTL speed feedback technology box will not operate.

Take special care wiring the encoders to the option due to the low level of the signals.

All wiring to the Speed Feedback option should be made in screened cable. Preferably, use cable with an overall screen and a screen over each individual pair. To ensure compliance with the EMC Directive the overall cable screen should be connected to the encoder body and to the cable clamp.

*Recommended cable:*

- Belden equivalent 8164 - overall screen and pairs individually screened
- Belden equivalent 8777 - pairs individually screened, SSD Drives Part No CM052666

# Initial Set-up

## Configuring the 605C Inverter

**MMI Menu Map**

- 1 SETUP PARAMETERS
- 2 FUNCTION BLOCKS
- 3 INPUTS & OUTPUTS
- 4 ENCODER
  - ENCODER MODE
  - ENCODER LINES
  - ENCODER INVERT
  - ENCODER RESET
  - ENCODER SUPPLY
  - ENCODER SPEED
  - ENCODER SPEED
  - ENCODER SPEED
  - ENCODER POSITION

Using the Operator Station (MMI) or other suitable PC programming tool, the ENCODER function block requires configuring before the HTTL option can be used.

*ConfigEd Lite is SSD Drives' Windows-based block programming software.*

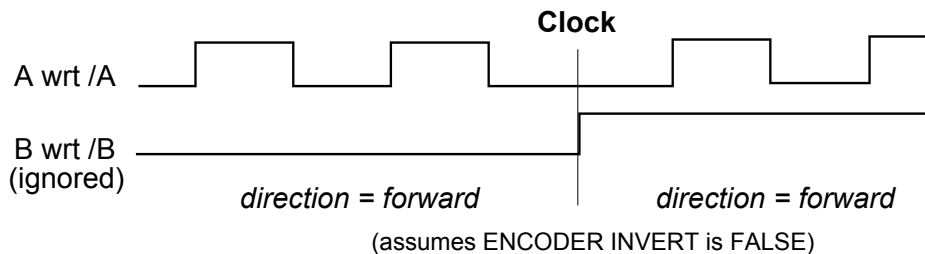
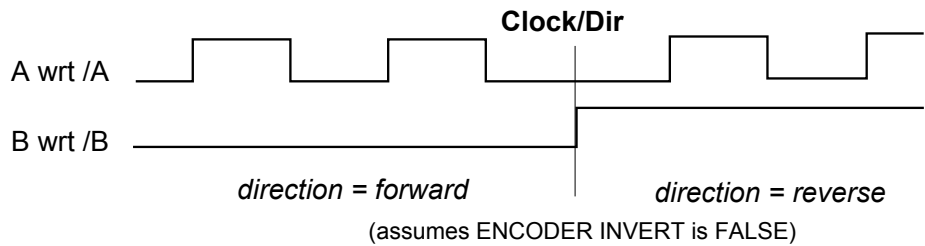
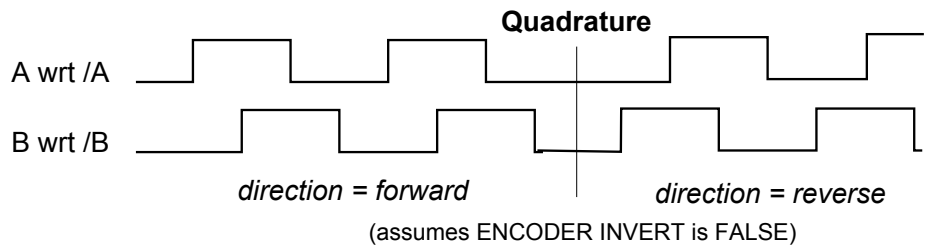
ENCODER	
SPEED Hz [568]	0.0 Hz
SPEED RPM [569]	0 n/min
SPEED % [749]	0.00%
POSITION [748]	0
QUADRATURE - [565] MODE	
1000 - [566] LINES	
FALSE - [567] INVERT	
FALSE - [747] RESET	
10.0V - [761] SUPPLY	

### Parameter Descriptions

#### MODE

*Range: Enumerated, see below*

This must be set to QUADRATURE, CLOCK/DIR or CLOCK.



*Enumerated Value : Encoder Mode*

- 0 : QUADRATURE
- 1 : CLOCK/DIR
- 2 : CLOCK

**LINES***Range: 1 to 10000*

The number of lines must be set to match the type of encoder being used. Incorrect setting of this parameter will result in an erroneous speed measurement.

**INVERT***Range: FALSE / TRUE*

When TRUE, changes the sign of the measured speed and the direction of the position count.

**RESET***Range: FALSE / TRUE*

When TRUE, the POSITION output is set (and held) at zero.

**SUPPLY***Range: 10.0 to 20.0V*

Approximate encoder supply voltage.

**SPEED Hz***Range: xxx.xHz*

Speed feedback in Hz.

**SPEED RPM***Range: xxxxx n/min*

Speed feedback in RPM.

**SPEED %***Range: xxx.xx%*

Speed feedback as a percentage of MAXIMUM SPEED.

**POSITION***Range:*

(increments @ 4 x line rate, i.e. 1 revolution = 4000 for a 1000 line encoder)

Number of encoder "counts" from when RESET was set to FALSE. The value will increment or decrement depending on the direction the encoder is rotated. The value will "wrap around" between 32767 and -32768.

## Configuring the 690+ Inverter

### MMI Menu Map

1	SETUP
2	MOTOR CONTROL
3	FEEDBACKS
	ENCODER SUPPLY
	ENCODER LINES
	ENCODER INVERT
	QUADRATIC TORQUE
	DC LINK VOLTS
	TERMINAL VOLTS
	SPEED FBK RPM
	SPEED FBK HZ
	SPEED FBK %
	ENCODER COUNT
	TORQUE FEEDBACK
	FIELD FEEDBACK
	MOTOR CURRENT %
	MOTOR CURRENT A

Using the Operator Station (MMI) or other suitable PC programming tool, this function block requires configuring before the HTTL option can be used.

*ConfigEd Lite is SSD Drives' Windows-based block programming software.*

Ranges for some outputs are given as “—.xx %”, for example, indicating an indeterminate integer for the value, to two decimal places.

Note that only parameters relevant to the Encoder are described below.

## Parameter Descriptions

### ENCODER SUPPLY

*Range: 10.0 to 20.0V*

Set this to the supply voltage required by the encoder.

### ENCODER LINES

*Range: 250 to 1000000*

The number of lines must be set to match the type of encoder being used. Incorrect setting of this parameter will result in an erroneous speed measurement.

\*\* Set to a value depending on the overall “power build “ of the Inverter.

### ENCODER INVERT

*Range: FALSE/TRUE*

Used to match the encoder direction to the motor direction. When TRUE, it changes the sign of the measured speed and the direction of the position count.

*It is especially necessary to set up this parameter when in CLOSED-LOOP VEC mode, as the encoder direction must be correct for this mode to operate.*

### SPEED FEEDBACK RPM

*Range: —.xx rpm*

The mechanical speed of the motor shaft in revolutions per minute.

### SPEED FEEDBACK HZ

*Range: —.xx Hz*

This parameter changes according to the CONTROL MODE (MOTOR DATA function block):

- In CLOSED-LOOP VEC mode, or SENSORLESS VEC mode, the parameter shows the mechanical speed of the motor shaft in revolutions per second.
- In VOLTS / Hz mode, the parameter shows the drive output frequency.

### SPEED FEEDBACK %

*Range: —.xx %*

Shows the mechanical speed of the motor shaft as a percentage of the user maximum speed setting (MAX SPEED in the SETPOINT SCALE function block).

### ENCODER COUNT

*Range: —.*

(increments/decrements @ 4 x line rate, i.e. 1 revolution = 4000 for a 1000 line encoder)

This is a 16-bit register which is incremented or decremented by the pulses from the encoder. It is useful to check that the encoder is operating, and to measure the encoder lines, if this is not known. Rotate the motor shaft through 1 revolution and note the difference between readings at the start and finish. The difference should be 4 times the encoder lines. For greater accuracy, rotate the shaft through several revolutions.

The direction of count is unaffected by ENCODER INVERT.

### Feedbacks


	DC LINK VOLTS	[ 75]	0 V
	TERMINAL VOLTS	[1020]	0 V
	SPEED FEEDBACK RPM	[569]	0.00 rpm
	SPEED FEEDBACK HZ	[568]	0.00 Hz
	SPEED FEEDBACK %	[749]	0.00 %
	ENCODER COUNT	[1016]	0
	TORQUE FBK	[ 70]	0.00 %
	FIELD FBK	[ 73]	0.00 %
	MOTOR CURRENT %	[ 66]	0.00 %
	MOTOR CURRENT	[ 67]	0.0 A
10.0 V	[761] ENCODER SUPPLY		
** 2048	[566] ENCODER LINES		
FALSE	[567] ENCODER INVERT		
FALSE	[ 50] QUADRATIC TORQUE		

## SSD Drives Approved Encoders

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Recommended Encoder (12mm bore)	Hengstler: SSD Drives Part Number:	RI 58TD//2048ED.37IF DD464475U012
Alternative Encoders (20mm bore)	Hengstler: SSD Drives Part Number:	RI 76TD/2048ED-4N20IF DD464475U020

Encoders are available from Hengstler in other accuracies such as 500 lines/rev or 2000 lines/rev to suit the application.

ISS.	MODIFICATION	ECN No.	DATE	DRAWN	CHK'D
1	Initial Issue (HA467152U001)	13059	22/6/99	CM	AFL
2	Differential input voltage corrected pages 1 & 3, earthing screw detail added page 2, approved encoders list updated on page 6.	13702	10/8/99	CM	AFL
3	Removed encoder body screen connections in diagrams on page 4.	16449	04/01/02	CM	AFL
4	Factory settings changed for option switches.	17759	03/11/03	CM	AFL
5	Company name change.	18354	22/11/05	CM	AFL
6	Manual combined with HA467427U001, Issue 3.	19165	15/12/05	CM	AFL
FIRST USED ON		MODIFICATION RECORD			
		HTTL Speed Feedback Technology Box			
		DRAWING NUMBER			SHT. 1
		ZZ467152C001			OF 1